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Consciousness and Depth of Anesthesia Assessment Based on Bayesian Analysis of EEG Signals

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4 Abstract—This study applies Bayesian techniques to analyze EEG signals for the assessment of the consciousness and depth of 5 6 anesthesia (DoA). This method takes the limiting large-sample nor-7 mal distribution as posterior inferences to implement the Bayesian paradigm. The maximum a posterior (MAP) is applied to denoise 8 the wavelet coefficients based on a shrinkage function. When the 9 anesthesia states change from awake to light, moderate, and deep 10 anesthesia, the MAP values increase gradually. Based on these 11 changes, a new function B_{DoA} is designed to assess the DoA. The 12 13 new proposed method is evaluated using anesthetized EEG recordings and BIS data from 25 patients. The Bland-Alman plot is used 14 to verify the agreement of $B_{\mathrm{D\,o\,A}}$ and the popular BIS index. A 15 correlation between $B_{\mathrm{D\,o\,A}}$ and BIS was measured using predic-16 17 tion probability P_K . In order to estimate the accuracy of DoA, the effect of sample n and variance τ on the maximum posterior 18 probability is studied. The results show that the new index accu-19 20 rately estimates the patient's hypnotic states. Compared with the 21 BIS index in some cases, the B_{DoA} index can estimate the patient's hypnotic state in the case of poor signal quality. 22

Index Terms—Bayesian, depth of anesthesia (DoA), electroen cephalogram (EEG), maximum a posterior (MAP), maximum
 posterior probability (MPP), wavelet transform.

I. INTRODUCTION

NESTHETISTS seek an early warning of a patient's level 27 of hypnosis in real time. A number of methods have been 28 developed over the years to detect the level of consciousness 29 and determine the depth of anesthesia (DoA), such as clinical 30 signs (systolic blood pressure, heart rate, sweating, and tears), 31 32 spontaneous surface electromyogram, heart rate variability, the minimum alveolar concentration, lower esophageal contractility 33 (LOC), and isolated forearm technique (IFT). However, these 34 methods are not reliable and could not achieve the desired accu-35 racy of anesthetic depth, as individual patients have variability 36 37 and various factors, such as the degree of stimulation, pain induced by surgery and the use of concomitant analgesic drugs. It 38

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is impossible to gain a constant level of consciousness through 39 precalculating the exact dose of anesthetics. Clinical investiga-40 tions and individual cases report that some patients had been 41 aware during the anesthesia at times when there were no ab-42 normalities in blood pressure and heart rate [1]. LOC was not 43 reliable for detecting of inadequate anesthesia when the primary 44 anesthetic agent was used [2]. In the IFT method, patients were 45 asked to move their fingers to check the level of the DoA. How-46 ever, some patients could hear the commands but were unable 47 to move the isolated arm. The incidence of movement with IFT 48 could vary with the choice of anesthetic [3], [4]. 49

Results from both human and animal studies demonstrate that 50 changes in electroencephalogram (EEG) with anesthesia pri-51 marily reflect hypnotic information [5]–[8]. Several DoA moni-52 toring devices were developed based on EEG. Currently, the BIS 53 monitor is widely used in hospitals. Although the algorithms of 54 these monitors are different and are not fully published, their 55 basic principles can be described as the following. The cere-56 bral state index is calculated using a fuzzy logic combination of 57 four subparameters of the EEG signals in the time domain and 58 the frequency domain [9]. The patient state index is the result 59 of a complex computation that combines weighted quantitative 60 EEG parameters reflecting many dimensions of brain electrical 61 activities [10]. Entropy index monitoring is based on the acqui-62 sition and processing of raw EEG and FEMG signals by using 63 Entropy algorithms to produce two parameters: state entropy 64 over the frequency range of 0.8–32 Hz, and response entropy 65 over the frequency range of 0.8-47 Hz [11]. In the Nacotrend 66 index, numerous quantitative features were extracted from the 67 time and the frequency domains, such as spectral parameters, 68 entropy measures, and autoregressive parameters [12]. The BIS 69 index is calculated from the following four parameters: 1) burst 70 suppression ratio (BSR); 2) quazi suppression index; 3) relative 71 β ratio; and 4) synchfastslow [13]. 72

These monitors are widely used in clinical practice and they 73 work satisfactorily most of the time. However, there are still 74 some criticisms in some special cases, such as not consistent 75 with the clinical observations [14], [15], not adequately de-76 tecting the transition between consciousness and unconscious-77 ness [16], and not responsive to some anesthetic agents [17]. The 78 time-domain analysis is used for the detection of epochs that rep-79 resent the electrical suppression of EEG signals. However, that 80 only happens in the case of very deep anesthesia. Therefore, 81 these analyses could not be used for the light anesthesia state 82 detection. 83

There are other developed methods for monitoring the DoA, such as wavelet transformation [18] and modified detrended moving average [19]. Recently, an adaptive time-frequency

analysis method based on ensemble empirical-model decom-87 position was used to analyze EEG signals for estimating the 88 DoA [20]. The spectral features of EEG signals were proposed 89 90 in [21] for separating the anesthetic effects. The Isomap-based estimation was used to assess neurophysiological changes dur-91 ing anesthesia [22]. The Hurst exponent and the wavelet trans-92 form was applied in multiscale rescaled range analysis algo-93 rithms to measure the anesthetic drug effects on brain activ-94 ity [23]. 95

The Bayesian method was also applied to analyze the EEG signals for the DoA [24], [25]. Rezek *et al.* presented an autoregressive class of polyspectral models in the variation Bayesian framework [24]. Their results showed that the estimated higher order spectra can give a significant improvement for the DoA. The midlatency auditory evoked potentials were used to estimate the DoA by a neural network and the Bayesian rule [25].

In this paper, a statistical method is developed to estimate the 103 DoA based on the Bayesian method. A denoising raw EEG data 104 105 technique is introduced using the maximum a posterior (MAP) to compute a new Bayesian-wavelet threshold for the large sam-106 107 ple posterior distribution. After denoising, the maximum posterior probability (MPP) is used to study the distribution of the 108 EEG signal. A new function B_{DoA} is designed to estimate the 109 anesthesia levels. To the best of our knowledge, this is the first 110 111 time a Bayesian method is proposed for assessing the DoA based on the EEG signal. 112

This paper is organized as follows. In Section II, the data ac-113 quisition and a Bayesian wavelet denoising method is presented 114 with a new threshold T_n . Section III introduces a relationship 115 between the maximum posterior and anesthesia states. A new 116 function B_{DoA} for monitoring the DoA is proposed in this sec-117 tion. The Bland-Altman method is used to test the degree of 118 agreement between the new index B_{DoA} and the BIS method in 119 Section IV. The experiment results are provided in Section V. 120 The discussion and the limitations of the study are presented in 121 Section VI. Finally, a short conclusion is drawn in Section VII. 122

123 II. BAYESIAN WAVELET DENOISING

124 A. Data Acquisition

Based on the relevant ethics approvals, the EEG data were 125 collected at the Toowoomba St. Vincent's Hospital. The formal 126 consents were obtained from 25 adult patients (ASA I or II, age 127 42-76 years, weight 64-130 kg, gender 10 F/15 M). Opera-128 tion types include minor orthopedics, peripheral generals, si-129 nus, thyroid, middle ear, abdominals, chest wall, laparoscopic 130 abdos, open abdos, lower abdos, perineal surgery, and laparo-131 scopic bowels. Typical drug administration included earlier 132 pharmaceuticals intravenous midazolam 0.05 mg/kg, fentanyl 133 1.5–3 μ g/kg, or alfentanil 15–30 μ g/kg. Intravenous propofol 134 was induction 1-3 mg/kg as clinically appropriate and mainte-135 nance with inhaled sevoflurane or desflurane in oxygen-enriched 136 air, or in 60% nitrous oxide in air. The airway was supported 137 by endotracheal intubation or by laryngeal mask airway as 138 indicated clinically. The timing of all intravenous dosing and 139 significant intraoperative events as indicated by the BIS mon-140 141 itor clock was recorded by the attending anesthetist. In the meantime, clinical observations by the attending anesthetists 142 during the data collection were also recorded for the 143 comparison. 144

The BIS Quatro sensor was attached to the patient's forehead. 145 Raw EEG data, BIS values, EMG, and signal quantity index 146 (SQI) were obtained and exported to a USB drive. Raw EEG 147 data were presented as a binary file documenting two channels 148 of unfiltered signals. Each EEG sample was a 16-bit signed 149 integer in units of $0.05 \ \mu$ V. The data were sampled at 128 times 150 per second for each channel. 151

B. Denoised Method

A noise EEG signal y_i of size n can be presented as

$$y_i = x_i + \varepsilon, i = 1, 2, \dots, n \tag{1}$$

where x_i is the true EEG signal and ε represents a noise which is 154 the sequence of independent and identically distributed random 155 variable. In the wavelet domain, a transform of y_i has the form 156 of 157

$$d = \hat{d} + \hat{\varepsilon} \tag{2}$$

where $d = Wy; \hat{d} = Wx; \hat{\varepsilon} = W\varepsilon; y = y_1, ..., y_n; x = x_1, ...,$ 158 $x_n;$ and $\varepsilon = \varepsilon_1, ..., \varepsilon_n.$ 159

Here, W is an orthogonal matrix, d is a noisy wavelet coefficient, \hat{d} is the true coefficient, and $\hat{\varepsilon}$ is noise. Our goal is to estimate \hat{d} from the noise observation d. The supposition to test is $H_0: \hat{d} = 0$ versus $H_1: \hat{d} \neq 0$.

A Bayesian wavelet threshold was proposed in [29]-[31]. 164 Prior information with Bayesian estimation techniques was ap-165 plied for the wavelet-based denoising. The MAP was used to es-166 timate d from the noisy observation d. A large sample posterior 167 distribution and approximations were presented by Press in [32]. 168 The limiting large-sample normal distribution was adopted for 169 posterior inferences of implementing the Bayesian paradigm. 170 In [33], a larger posterior mode for the wavelet threshold was 171 proposed by Cutillo et al. based on the MAP with the threshold 172

$$T = 2\sigma\sqrt{2k - 1}, k > 1/2.$$
 (3)

C. Statistic Model

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For the model, the assumption is made that the wavelet coefficient d is normally distributed with the parameters μ and σ^2 , 175 and its density function $p(d|\mu, \sigma^2)$ is given by 176

$$p(d|\mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{1}{2\sigma^2}(d-\mu)^2\right\}.$$
 (4)

If $d \sim N(\mu, \sigma^2)$, then $E(d) = \mu$ and $V(d) = \sigma^2$. The parameter μ of the normal distribution is determined by the expected 178 value and the parameter σ^2 by the variance of the random variable d. 180

Suppose we have normal observations $d|\hat{d} \sim N(\hat{d}, \sigma^2)$, 181 where σ is known and the prior distribution for \hat{d} is 182

$$\hat{d}|\lambda^2 \sim N(\mu, \lambda^2), \lambda^2 \sim (\lambda^2)^{-nk}, k > 0$$
(5)

where λ^2 is the single unknown hyperparameter. Here, it is 183 assumed that the parameters \hat{d} are independent and identi-184

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cally distributed, and conditional on other parameters, such as $\hat{d} \sim N(\mu, \lambda^2)$. Consider a conjugate prior to $p(d|\hat{d})$ and $p(\hat{d}|\lambda^2)$, the hierarchical Bayes induces the following structure [32]:

$$\lambda^2 \sim p(\lambda^2), \hat{d}|\lambda^2 \sim p(\hat{d}|\lambda^2), d|\hat{d} \sim p(d|\hat{d}).$$
(6)

The likelihood function $l(d|\hat{d})$ is the probability of observing d being conditional on the values of \hat{d} . The prior distribution on \hat{d} [33] is

$$p(\hat{d}) = \int p(\hat{d}|\lambda^2) p(\lambda^2) d(\lambda^2).$$
(7)

The posterior distribution expresses the information of dbased on both the sample data and the prior information [33]

$$p(d, \hat{d}) = \int p(d|\hat{d})p(\hat{d}|\lambda^2)p(\lambda^2)d(\lambda^2).$$
(8)

193 D. New Bayesian Wavelet Threshold

194 The MAP estimator developed for the Gaussian case is

$$p(d, d) \propto p(d, d) \propto l(d).$$
 (9)

Here, $l(\hat{d})$ is the likelihood [33]

$$l(\hat{d}) = e^{-\frac{1}{2\sigma^2}(d-\hat{d})^2} (\hat{d}-\mu)^{2\left(\frac{1}{2}-nk\right)}.$$
 (10)

The goal here is to find the parameters \hat{d} that maximize the posterior probability. The logarithm of the posterior is proportional to

$$\log \left\{ p(d, \hat{d}) \right\} \propto \log \left\{ l(\hat{d}) \right\} = L(\hat{d})$$
$$= \left\{ -\frac{1}{2\sigma^2} (d - \hat{d})^2 \right\} + (1 - 2nk) \log \left(\hat{d} - \mu \right).$$
(11)

199 Maximum posterior estimators are asymptotically equivalent 200 to the classical maximum likelihood estimators. The eventual 201 models of the posterior $p(d|\hat{d})$ happen when $L(\hat{d})$ maximizes. 202 The derivative of $L(\hat{d})$ with respect to \hat{d} is

$$\frac{\partial L(\hat{d})}{\partial \hat{d}} = \frac{\hat{d}^2 - (\mu + d)\hat{d} + \mu d + \sigma^2(2nk - 1)}{\sigma^2(\mu - d)}.$$
 (12)

203 Setting the derivative equal to 0, we obtain

$$d \ge \mu + 2\sqrt{\sigma^2(2nk - 1)}.\tag{13}$$

To estimate the noise variance σ^2 from the noisy wavelet coefficients, the finest scale wavelet coefficient a_1 is used to compute a median estimator in [26]–[28] as

$$\sigma^2 = \frac{\text{median}(|a_1|)}{0.6745}.$$
 (14)

207 Combining (13) and (14), a new threshold T_n is defined as

$$T_n = \log\left(\mu + 2\sqrt{\sigma^2(2nk - 1)}\right) \tag{15}$$

208 with

$$\mu = \operatorname{mean}(x). \tag{16}$$

The B_{DoA} function is used to compare the efficiency of two denoising thresholds which were presented in (3) and (15). The detail of B_{DoA} will be presented in the next section (see (24)).



Fig. 1. Comparison between the two denoising thresholds: (a) B_{DoA} trend using the threshold in (3). (b) B_{DoA} trend using the new proposed Bayesian threshold in (15).

In Fig. 1(b), B_{DoA} clearly shows the changes of patient's states 212 from awake state to deep anesthesia, and from general anesthesia to awake. This B_{DoA} trend used the new proposed Bayesian 214 threshold in (25). In contrast, the trend of B_{DoA} which used 215 the threshold in (3) has some spike noise during general anesthesia period as shown in Fig. 1(a). This indicates that our new Bayesian threshold is better than the threshold in (3) for denoising raw EEG signals. 219

In this section, we derive the estimate method for monitoring 221 the DoA using a Bayesian method. If the EEG signal is presented 222 by x and denotes the set of unknown parameters by θ , the 223 likelihood function $f(x|\theta)$ is the probability of observing the 224 data x being conditional on the values of parameter θ . The prior 225 distribution for θ is $\pi(\theta)$. Bayesian's theorem gives the posterior 226 probability density function (pdf) for parameter θ as 227

$$f(\theta|x) = \frac{f(x|\theta)\pi(\theta)}{\int f(x|\theta)\pi(\theta)d\theta}$$
(17)

where f denotes the joint pdf of the data and π denotes the prior 228 pdf of θ . If f is replaced by the likelihood function $L(\theta|x)$, we 229 have 230

$$f(\theta|x) = \frac{L(x|\theta)\pi(\theta)}{\int L(x|\theta)\pi(\theta)d\theta}.$$
(18)

Suppose the EEG signal x has the normal observation $x|\theta \sim 231$ $N(\theta, \sigma^2)$, where sigma is known and the prior distribution for 232 θ is $\theta \sim N(\mu, \tau^2)$. We have 233

$$E(\theta|x) = \mu + \frac{\tau^2}{\sigma^2 + \tau^2} (x - \mu) = \frac{\sigma^2 \mu + \tau^2 x}{\sigma^2 + \tau^2}$$
(19)

$$\operatorname{Var}(\theta|x) = \frac{\tau^2 \sigma^2}{\sigma^2 + \tau^2}.$$
(20)

The posterior for θ is the normal pdf as

$$y_{\theta} = f(\theta|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(\theta-\mu)^2}{2\sigma^2}}.$$
 (21)



Fig. 2. Posterior, likelihood, and prior density function of the EEG signal with patient 19.



Fig. 3. Comparison between the maximum of different posterior distributions, corresponding to different anesthesia states in four sample ranges.

Fig. 2 shows the posterior, prior, and likelihood of patient's 235 EEG data in the case of normal distributions. The posterior, 236 likelihood and, prior density functions are shown together for 237 the unknown parameter θ in this figure. The posterior and like-238 lihood density functions are considerably more concentrated 239 around their maximum values than the prior density function. A 240 posterior density function is used to characterize the values of 241 the parameters for the EEG data. 242

243 A. MPP of the θ Distribution

Let MPP be the maximum value of the posterior of y_{θ} , to give

$$MPP = \max(y_{\theta}). \tag{22}$$

MPP will be used to estimate the DoA. Fig. 3(a) shows four posterior graphs of y_{θ} in different states of anesthesia. The maximum values of the posterior in Fig. 3(a) have changed from low

 TABLE I

 Relation Between the Anesthesia States and the MPP for a Patient

Anaesthesia states	BIS value	Range	MPP
Awake	80-97	Range 1: 0-50 s	MPP ₁ =0.0954
Light anaesthesia	59-68	Range 3: 230-280 s	MPP ₃ =0.1065
Moderate anaesthesia	41-43	Range 2: 100-150 s	MPP ₂ =0.1083
Deep anaesthesia	25-26	Range 4: 480-530 s	MPP ₄ =0.1316

values to high values when the BIS trend of patient 19 changed 248 from awake to the deep anesthesia states in Fig. 3(b). Patient 19 249 was a 74 yr old, 100 kg male. BIS values were recorded between 250 09:21:36 am and 10:33:44 am. Anesthesia induction was with 251 intravenous midazolam 3 mg at 09:22:00, alfentanil 1000 μ g at 252 09:22:03, and propofol 120 mg at 09:25:53. At 09:25:55, inhaled 253 sevoflurane and nitrous oxide were introduced. The rectangles 254 1, 2, 3, and 4 in Fig. 3(a) cover the posteriors 1, 2, 3, and 4 255 which are corresponding to the ranges 1, 2, 3, and 4 in Fig. 3(b). 256 Range 1 indicates the awake state with the BIS values from 80 257 to 97. Range 2 shows the moderate anesthesia state with the BIS 258 values from 41 to 43. Range 3 represents the light anesthesia 259 state with the BIS values from 59 to 68; while range 4 is the 260 deep anesthesia state with the BIS values from 25 to 26. 261

Table I presents a relationship between the anesthesia states 262 and the MPP. When the anesthesia states change from awake 263 to light, moderate, and deep anesthesia, the MPP values in-264 crease from 0.0954, 0.1065, 0.1083, and 0.1316, respectively. 265 These changes are also shown in Fig. 3, corresponding to the 266 four ranges in the four rectangles. These rectangles are used to 267 connect the BIS trend and the posterior distribution in different 268 ranges. The ranges for computing the MPP in Fig. 3 are selected, 269 based on the levels of the anesthesia states. Each individual pos-270 terior distribution is computed within its own range and then 271 compared on the same axis. The BIS trend shows the changes 272 of anesthesia states over time. 273

B. Monitor the DoA

The MPP values have different scales for individual patients. 275 Therefore, their values are converted to a common scale through 276 normalization. A new scale for the MPP in the range of [0, 1] is 277 MPP = MPP/max(MPP). Fig. 4 presents a scatter plot of the BIS 278 and the MPP for 25 patients. The BIS values are on the x-axis 279 in the range of [0, -100] and the MPP values are on the y-axis 280 in the range of [0, -1]. A least-squares curve-fitting method is 281 used to find the straight line by minimizing the distance from 282 each point to this line. The line equation we obtained is 283

$$MPP = -0.0077BIS + 0.87.$$
 (23)

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This line is the best fit to a set of data points for minimizing the sum of the squared distances between the line and the data points. Based on the relation of the MPP values and the BIS values in (32) when anesthesia states change from awake to deep anesthesia, a new function is proposed to estimate the 289



Fig. 4. Scatter plot and regression line of the BIS and MPP for 25 patients.



Fig. 5. Scatter plot, histograms, and regression line for the B_{DoA} and BIS values.

290 anesthesia levels as

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$$B_{\text{DoA}} = (1 - \text{MPP}) \times 100 + V_{\text{OFFSET}}.$$
 (24)

Fig. 5 presents a scatter plot of the B_{DoA} and the BIS values, and their histograms on the horizontal and vertical axes. The *r*-squared values $r^2 = 0.9285$ and r = 0.93 show a strong correlation between the B_{DoA} and the BIS. The statistical significance was assumed at probability levels of p < 0.005.

IV. AGREEMENT OF THE B_{DOA} and the BIS

To evaluate and compare our proposed method with other established methods, such as the BIS, the Bland–Altman method [36] is used to test the degree of the agreement between the proposed and BIS methods.

Defining the difference of the B_{DoA} and the BIS index as (B_{DoA} -BIS), the mean difference is $d_{\text{ff}} = \text{mean}(B_{\text{DoA}}-\text{BIS})$, and the standard deviation of the differences is SD = std(B_{DoA} -BIS). If the differences are normally distributed, 95% of the differences lie between (d_{ff} -2SD) and (d_{ff} - 2SD). The calculation of the 95% limits of agreement is based on the assumption



Fig. 6. Distribution of the differences ($B_{D,0A}$ -BIS) and the normal fitting.



Fig. 7. Bland–Altman plot shows the difference $(B_{DOA}-BIS)$ versus the average of values measured with 95% limits of agreement.

that the differences are normally distributed. The distribution of 307 the differences can be checked by drawing a normal plot or 308 histogram. 309

Fig. 6 presents the fitting of the normal distribution of 310 the differences (B_{DoA} —BIS). In this figure, the distribution 311 of the differences matches well with the normal fitting. The 312 Bland–Altman plot is presented in Fig. 7. The Bland–Altman 313 method calculates the mean difference between two methods 314 of the measurement (the "bias") and 95% limits of agreement 315 as the mean difference (2SD). The Bland-Altman can include 316 an estimation of confidence intervals for the bias and limits 317 of agreement. In Fig. 7, there is a bias of 0.3379. The upper 318 limit of agreement is $(d_{\rm ff} + 2SD) = 16.1$, and the lower limit 319 is $(d_{\rm ff} - 2\text{SD}) = -11.28$. The 94.73% (17.500/18.473) limit 320 of agreement presents a visual judgment of how well the two 321 methods of the measurements agree. 322

Prediction probability P_K was assessed as described by Smith 323 et al. [37] as a statistical test to assess the capability of a classifier 324 to discern different levels of anesthesia. In this study, P_K is 325 calculated using the PK tool 1.2 by Denis et al. [38]. A value of 326



Fig. 8. EEG histogram is fitted to the different probability densities: normal, gamma, Rayleigh, extreme, inverse Gaussian, and exponential.

³²⁷ $P_K = 0.5$ means that the index predicts the observed state no ³²⁸ better than 50/50 chance, and a value of $P_K = 1.0$ means that the ³²⁹ index always predicts the observed state correctly. A value of ³³⁰ p < 0.05 was considered significant. P_K was calculated for each ³³¹ patient. An average of these P_K (mean(P_K) = 0.807) preserves ³³² a good correlation between expected index values B_{DoA} and ³³³ BIS.

334 V. EXPERIMENT RESULTS

335 A. Probability Distribution of the EEG Signal

Assuming that the EEG data are the observations from a con-336 tinuous probability distribution, to model the behavior of those 337 data, the modeling will then begin by studying the distribution 338 of the data. In practice, it is difficult to know exactly the prob-339 ability distribution of the observations. A simple approach to 340 model the behavior of the data is to form a histogram of the 341 data. Fig. 8 plots the histogram of the EEG signal in the data 342 vector using a number of bin bars in the histograms. The EEG 343 histograms are fitted to the different probability densities, such 344 as normal, gamma, Rayleigh, extreme, inverse Gaussian, and 345 exponential. As shown in Fig. 8(a), the normal probability den-346 sity model matches the histograms well. Therefore, the normal 347 pdf is used to compute the pdf of the EEG signal. 348

349 B. Parameter Estimation

If the hyperparameters (μ and τ) are known, the posterior distribution for θ can be obtained as

$$\theta|x \sim N\left(\frac{\sigma^2 \mu + \tau^2 x}{\sigma^2 + \tau^2}, \frac{\tau^2 \sigma^2}{\sigma^2 + \tau^2}\right).$$
(25)

In practice, the situation parameters n and τ vary over time with different patients. Therefore, the B_{DoA} function may not be accurate for the large samples of patients. In order to estimate the accuracy of DoA, the effect of parameters n and τ on the MPP is studied with different values. With sample n and the sample mean $\bar{X} = 1/n \sum_{i=1}^{n} x_i$, to give

$$\theta|x_1, x_2, \dots, x_n \sim N(\mu_p, \sigma_p) \tag{26}$$



Fig. 9. Impacts of n and τ values on the posterior values. (a) MAP values increase when the sample n increases. (b) MAP values decrease when the variance τ increases.

TABLE II B_{DoA} Values in Awake State With Different Samples (n)and Variance τ Values, BIS = 80-100

$\tau \setminus k$	1	5	10	15	20	25	30
5	91.5	89.5	87.4	85.7	84.1	82.7	81.4
10	95.0	92.1	89.5	87.5	85.7	84.1	82.7
15	95.9	92.6	89.9	87.8	86.0	84.4	83.0
20	96.3	92.8	90.1	87.9	86.1	84.5	83.1
25	96.5	92.9	90.2	88.0	86.2	84.6	83.1
30	96.7	93.0	90.2	88.0	86.2	84.6	83.1
35	96.7	93.0	90.2	88.0	86.2	84.6	83.1
40	96.8	93.1	90.2	88.1	86.2	84.6	83.1
45	96.8	93.1	90.2	88.1	86.2	84.6	83.2
50	96.8	93.1	90.3	88.1	86.2	84.6	83.2

with

$$\mu_p = \frac{\sigma^2 \mu + n\tau^2 \bar{X}}{\sigma^2 + n\tau^2}, \sigma_p = \frac{\tau^2 \sigma^2}{\sigma^2 + n\tau^2}.$$
 (27)

The impacts of the value of n and τ on the posterior values are 359 shown in Fig. 9. In Fig. 9(a), when n has the values of 100, 1000, 360 and 10000, the posteriors get the maximum values as 0.0074, 361 0.2263, and 0.6737, respectively. The MAP value will have a 362 high value with a large sample n and vice versa. In Fig. 9(b), 363 when τ has the values of 5, 10, 20, and 40, the posteriors get 364 the maximum values as 0.1072, 0.0820, 0.0744, and 0.0724, 365 respectively. 366

C. B_{DoA} Estimation Based on Bayesian Parameters

In this section, B_{DoA} values are considered based on the 368 change of the different samples (n) and variance τ values. Four 369 states of anesthesia are studied such as awake, light anesthesia, 370 moderate anesthesia, and deep anesthesia states, corresponding 371 to the BIS value ranges at 80–100, 60–80, 40–60, and 20–40, 372 respectively. The simulation results are presented in Tables II-373 V. The samples (n) are chosen with the values as $n = 128 \times k$, 374 with k = 1, 5, 10, 15, 20, 30. The variance τ are chosen with 375

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TABLE III $B_{\rm DoA}$ Values in Light Anesthesia State With Different Samples (n) and Variance τ Values, BIS = 70–80

$\tau \setminus k$	1	5	10	15	20	25	30
5	90.8	87.2	83.7	80.9	78.4	76.2	74.1
10	94.0	89.2	85.2	82.1	79.5	77.2	75.1
15	94.8	89.6	85.5	82.4	79.7	77.4	75.2
20	95.1	89.7	85.6	82.5	79.8	77.4	75.3
25	95.2	89.8	85.7	82.5	79.8	77.5	75.3
30	95.3	89.9	85.7	82.5	79.9	77.5	75.4
35	95.4	89.9	85.7	82.6	79.9	77.5	75.4
40	95.4	89.9	85.7	82.6	79.9	77.5	75.4
45	95.4	89.9	85.8	82.6	79.9	77.5	75.4
50	95.4	89.9	85.8	82.6	79.9	77.5	75.4

TABLE IV $B_{\rm DoA}$ Values in Moderate Anesthesia State With Different Samples (n) and Variance τ Values, BIS = 40–55

$\tau \setminus k$	1	5	10	15	20	25	30
5	86.6	74.6	65.1	57.7	51.4	45.9	41.0
10	88.5	75.6	65.8	58.2	51.9	46.4	41.4
15	88.9	75.8	65.9	58.3	52.0	46.4	41.5
20	89.0	75.8	65.9	58.4	52.0	46.5	41.5
25	89.1	75.9	66.0	58.4	52.0	46.5	41.5
30	89.1	75.9	66.0	58.4	52.1	46.5	41.5
35	89.2	75.9	66.0	58.4	52.1	46.5	41.5
40	89.2	75.9	66.0	58.4	52.1	46.5	41.5
45	89.2	75.9	66.0	58.4	52.1	46.5	41.5
50	89.2	75.9	66.0	58.4	52.1	46.5	41.5

376 the values as $\tau = 5 \times m$, with m = 1, 2, ..., 10. In Table II, in awake state, the $B_{\rm DoA}$ values are in the range of 80–100, except 377 the change of n and τ values. However, in Tables III and IV, 378 the B_{DoA} values are only correct with the situations when the 379 values n are $128 \times k$, $128 \times k$, and $128 \times k$, with k = 20, 25, 380 and 30. Finally, in Table V, the B_{DoA} values are correct with 381 the situations when the values of k are 20 and 25. Summarizing 382 for different cases of anesthesia states, the sample n is chosen 383 in the range of [2560, 3200], and τ values can vary from 5 to 384 50. 385

386 D. Choosing the θ Distribution Function

In this section, the B_{DoA} values are considered with different θ distributions, such as linear function, logarithm function, normal cumulative distribution function (cdf), and normal pdf. In order to select a best θ distribution, the B_{DoA} values are collected and compared with patient's states and the BIS values. For the linear distribution for θ [see Fig. 10(a)], the B_{DoA} trend correctly reflects the clinical changes of the patient. In Fig. 10(b),

 $\begin{array}{c} \text{TABLE V}\\ B_{\text{DoA}} \text{ Values in Deep Anesthesia State With Different Samples } (n)\\ \text{ and Variance } \tau \text{ Values, BIS} = 20\text{--}35 \end{array}$

$\tau \setminus k$	1	5	10	15	20	25	30
5	82.6	64.6	50.7	40.1	31.2	23.5	16.5
10	84.0	65.2	51.2	40.5	31.5	23.7	16.8
15	84.3	65.3	51.2	40.5	31.6	23.8	16.8
20	84.4	65.4	51.3	40.5	31.6	23.8	16.9
25	84.4	65.4	51.3	40.6	31.6	23.8	16.9
30	84.4	65.4	51.3	40.6	31.6	23.8	16.9
35	84.5	65.4	51.3	40.6	31.6	23.8	16.9
40	84.5	65.4	51.3	40.6	31.6	23.8	16.9
45	84.5	65.4	51.3	40.6	31.6	23.8	16.9
50	84.5	65.4	51.3	40.6	31.6	23.8	16.9



Fig. 10. Different θ distributions: linear function, logarithm function, normal CDF, and normal pdf are used to compute the B_{DoA} which were compared with the BIS trends.

the B_{DoA} trend changes from the range of 80–100 to the range 394 of 20–40 when the patient's state changes from consciousness 395 to unconsciousness. During the moderate anesthesia state, the 396 $B_{\rm DoA}$ trend is in the range of 40–50. In the emergence state, 397 the B_{DoA} trend increases from 50 to 95. With the logarithm 398 distribution θ in Fig. 10(b), the B_{DoA} trend is flat as shown in 399 Fig. 10(d). For the normal cdf in Fig. 10(c), the B_{DoA} trend in 400 Fig. 10(f) is not close to the BIS trend. 401

The normal cdf is

$$\theta_{\text{ncdf}} = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-\frac{(t-\mu)^2}{2\sigma^2}} dt.$$
(28)

402

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The normal pdf is

$$\theta_{\rm npdf} = F(x|\mu,\sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}.$$
 (29)



Fig. 11. Burst suppression happens from 390 to 397 s. (a) Comparison between B_{DoA} and BIS trends. B_{DoA} index can show the DoA values during the burst suppression time. (b) Sample EEG signal during the burst suppression time.

For the normal pdf distribution of θ in Fig. 10(g), the B_{DoA} trend in Fig. 10(h) shows the same result as the B_{DoA} trend in Fig. 10(b). In both cases, the B_{DoA} trends are close to the BIS trends. Therefore, the linear function and the normal pdf can be chosen for the θ distribution.

409 E. Burst Suppression EEG Pattern

During the deep anesthesia, the EEG voltage may change 410 from high activity to low or even isoelectricity. This pattern is 411 known as burst suppression. The BSR is a time-domain EEG 412 parameter developed to quantify this phenomenon (i.e., a flat 413 EEG or no significant electrical activity in the brain). The burst 414 suppression is recognized as those periods longer than 0.50 s, 415 during which the EEG voltage does not exceed approximately 416 $\pm 5.0 \,\mu V$ [6]. The B_{DoA} and BIS trends are shown in Fig. 11(a). 417 This figure shows the B_{DoA} values in the range of 13.3–15.5 sec-418 onds during burst suppression, lasted 4 s from 390 to 394 s. The 419 EEG signal during the burst suppression is shown in Fig. 11(b). 420 During this period, the EEG signal has an amplitude value lower 421 than 5.0 μ V. 422

423 F. Patient's State in the Case of Poor Signal Quality

The BIS index is a good monitor but in some cases BIS 424 index could not display the values on the screen when signal 425 quality indicator (SQI) was lower than 15. This paper claims 426 that B_{DoA} can display the DoA values in the case of poor signal 427 quality but the BIS could not. For these cases, the BIS monitor 428 displays a notice "Excessive artifact detected in signal". In the 429 recorded BIS data of excel file, the value -3276.8 was labeled 430 in these cases. In the BIS monitor, the signal quality indicator 431 (SQI) is a measure of the signal quality for the EEG channel 432 source and is calculated based on impedance data, artifacts, and 433 other variables. When the signal quality is too low to accurately 434 calculate a BIS value, the affected BIS value and other trends 435 will not be displayed on the screen. Potential artifacts may be 436 caused by poor skin contact (high impedance), muscle activity or 437 rigidity, head and body motion, sustained eye movements, etc. 438 Only "valid" BIS values are displayed on the monitor screen 439 440 when signal quality index (SQI) is above 15 [22].



Fig. 12. DoA values in the case of poor signal quality of Patient 12: a comparison between the B_{DoA} and BIS trends. From 0 to 180 s, when SQI is lower than 15, the B_{DoA} values can display the DoA values but the BIS cannot.



Fig. 13. During general anesthesia, the B_{DoA} values can display the DoA values but the BIS cannot when SQI is lower than 15.

Fig. 12 shows a case of poor signal quality of Patient 12 441 when patient's state changed from awake to anesthesia. Patient 442 12 was a 63 yr old, 72 kg, female. Surgery was undertaken from 443 10:31:33 am to 10:52:26 am. Drug administration consisted 444 of midazolam (4 mg) as a sedative drug at 10:31:35 am. At 445 10:31:55 am, alfentanil (1000 μ g) was used as strong pain relief 446 given only once during the operation. Parecoxib (40 mg) and 447 Propofol (160 mg) were used at 10:32:55 am and 10:33:30 448 am, respectively. At 10:33:35 am, desflurane and nitrous oxide 449 (N_2O) were started. From 0 to 180 s (10:31:33 am to 10:34:33) 450 am), the BIS cannot display the DoA values. The clinically 451 important transition from the awake state (BIS = 100) to deep 452 anesthesia (BIS = 33.6) is masked by this phenomenon (see 453 Fig. 12). In this case, the anesthetist could not use the BIS index 454 to estimate the state of the patient. 455

Another case of poor signal quality is presented in Fig. 13 dur-456 ing general anesthesia. However, the proposed B_{DoA} index can 457 compute and display the DoA index at times when SQI is lower 458 than 15 and the invalid BIS value did not display on the moni-459 tor screen. The proposed B_{DoA} displays are shown in Figs. 12 460 and 13. Compared with the BIS index in these cases, during the 461 periods of poor signal quality, the results of this Bayesian MMP 462 method better correlate with clinical observations. Those other 463 cases can be found when BIS values dropped as shown in Figs. 464 14 and 16(c). 465



Fig. 14. Comparison between the B_{DoA} and BIS trends in the case of poor signal quality in Patient 11.



Fig. 15. Comparison between the B_{DoA} and BIS trends in the case of poor signal quality in Patient 19.

There is a case where B_{DOA} goes wrong while BIS seems 466 to be reliable as shown in Fig. 15. At the awake state, B_{DoA} 467 drops two times to value 25 when BIS only drops one time. At 468 the second 1500, the BIS value increases but B_{DOA} decreases 469 at the recovery time. In this case, probably there are impedance-470 related artifacts that can arise from electrode drift on the skin. In 471 the other cases during general anesthetic, dropped B_{DoA} values 472 do not happen but the BIS does. 473

474 G. Testing Denoise Algorithm

In order to check the denoise result, the B_{DoA} function is 475 476 used for three parameters y, x, and ε in (1): $y = x + \varepsilon$. Here, y is a noise EEG signal, x is the EEG signal after denoising, 477 and ε is a noise. Fig. 16(a), (b), and (c) shows the B_{DoA} of 478 the raw EEG signal, noise, and the EEG signal after denoising, 479 respectively. $B_{\rm DoA}(y)$ and $B_{\rm DoA}(\varepsilon)$ trends are in the range of 480 96.5-100 and do not have any relation to the patient's states. In 481 contrast, $B_{\text{DoA}}(x)$ trend is close to the BIS trend. This means 482 that the denoising algorithm did not filter out any important 483 information regarding the DoA. 484

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VI. DISCUSSION

In this paper, clinically observed changes in conscious state were also observed and recorded by the attending anesthetist



Fig. 16. (a) $B_{\text{DoA}}(y)$: B_{DoA} of raw EEG signal, (b) $B_{\text{DoA}}(\varepsilon)$: B_{DoA} of noise, and (c) $B_{\text{DoA}}(x)$: B_{DoA} of EEG signal after denoising in Patient 4.

for comparison. The patients' responses were the overall (ex-488 perienced) clinical impressions which took into account patient 489 movement, lacrimation, heart rate, blood pressure, respiratory 490 effort, pupil status, and, importantly, what surgery the patient 491 had undergone. The two main components to create the anes-492 thetic state are hypnosis created with drugs, and analgesia cre-493 ated with the nitrous oxide. The earlier pharmaceuticals mida-494 zolam 4 mg and alfentanil 1000 μ g were induced. Most patients 495 might not remember but might well move in response to stimuli 496 after these drugs have been given. Loss of consciousness (LOC) 497 occurs reliably at about 30-60 s after intravenous propofol. As-498 sessment of LOC clinically was by lack of response to verbal 499 and tactile stimuli. Loss of the lash reflex was used in the case 500 of doubt. However, we did not have the plasmatic concentra-501 tions of sedative drugs. This could be a limitation of this study, 502 especially with a small number of patients. Data exported to 503 a USB drive and transferred to a portable computer for offline 504 analysis. The results were compared with the BIS in the simu-505 lation, the same as with real-time analysis. Therefore, extensive 506 testing with a larger set of subjects in real time is necessary 507 to further improve the method. Furthermore, clinical anesthe-508 sia scales, such as the observer's assessment of anesthesia and 509 sedation and drug concentrations, can be used as an additional 510 reference to improve the accuracy of the DoA estimation. 511

VII. CONCLUSION

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This paper studies a Bayesian method for denoising EEG sig-513 nals and estimating the hypnotic DoA. First, an adaptive thresh-514 old for Bayesian wavelet denoising is proposed. The wavelet 515 transform coefficients are modeled with prior probability distri-516 butions. A Bayesian technique is used to denoise the coefficients 517 based on this prior information and the likelihood function. A 518 new Bayesian threshold T_n is better than the threshold in [33] 519 for denoising raw EEG signals. 520

Second, a new index B_{DoA} is proposed based on the MPP 521 values. When the anesthesia states change from awake to light, 522 moderate, and deep anesthesia, the MPP values increase corre-523 spondingly. The Bland-Altman method is used to test the degree 524 of agreement between our proposed method and the BIS index. 525 The scatterplot indicates the agreement rates of 94.73% between 526 B_{DoA} and BIS indices. The result mean $(P_K) = 0.807$ preserves 527 a good correlation between the expected index values B_{DoA} and 528 BIS. 529

530 In order to estimate the accuracy of DoA, the effect of sample n and variance τ on MPP is studied. The MPP value will have 531 the high value with a large sample n and vice versa. For different 532 anesthesia states, the sample n is chosen in the range of [2560, 533 3200], and τ value can vary from 5 to 50. In order to select the 534 best θ distributions, the B_{DoA} values are collected and compared 535 with the patient's states and the BIS values. In the cases of the 536 linear function and the normal pdf, the B_{DoA} trends are close to 537 the BIS trends. Therefore, these functions are chosen for the θ 538 539 distribution.

The simulation results show that the new index accurately estimates patient's hypnotic states. In addition, B_{DoA} can reflect the clinical observations better than the BIS index during the periods of poor signal quality.

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