



Australian Government

**Cotton Research and
Development Corporation**

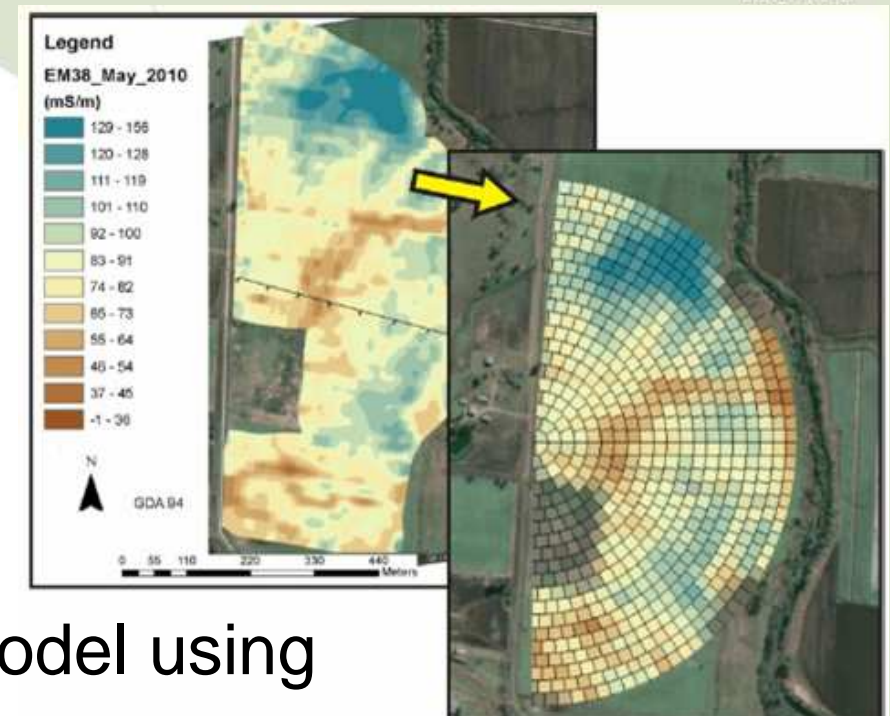


Development of a sensing system for automated cotton fruit load and vegetation estimation

**Dr Alison McCarthy and
Associate Professor Nigel Hancock**
National Centre for Engineering in Agriculture
mccarthy@usq.edu.au

VARIwise control framework

- VARIwise:
simulates and develops site-specific irrigation control strategies
- Steps for model-based strategies:
 1. Calibrate crop production model using input soil/plant parameters
 2. Repeatedly execute model with different irrigation volumes and timing to determine irrigation that produces the desired performance objective
- Plant parameters required to calibrate model:
leaf area index, square count, boll count and plant density



Cotton plant sensing



- Plant condition from visual attributes
 - vegetative growth, leaf area, flowering timeframe, boll capacity, plant density

- Plant density influences micro-climate
 - soil moisture extraction, light interception, humidity and wind movement
- ...which also influences:
 - plant height, branch development, fruit location and size

- Beneficial to automated irrigation control systems

Sensing systems for field crops



Commercially-available:

- Light sensors to measure leaf area index

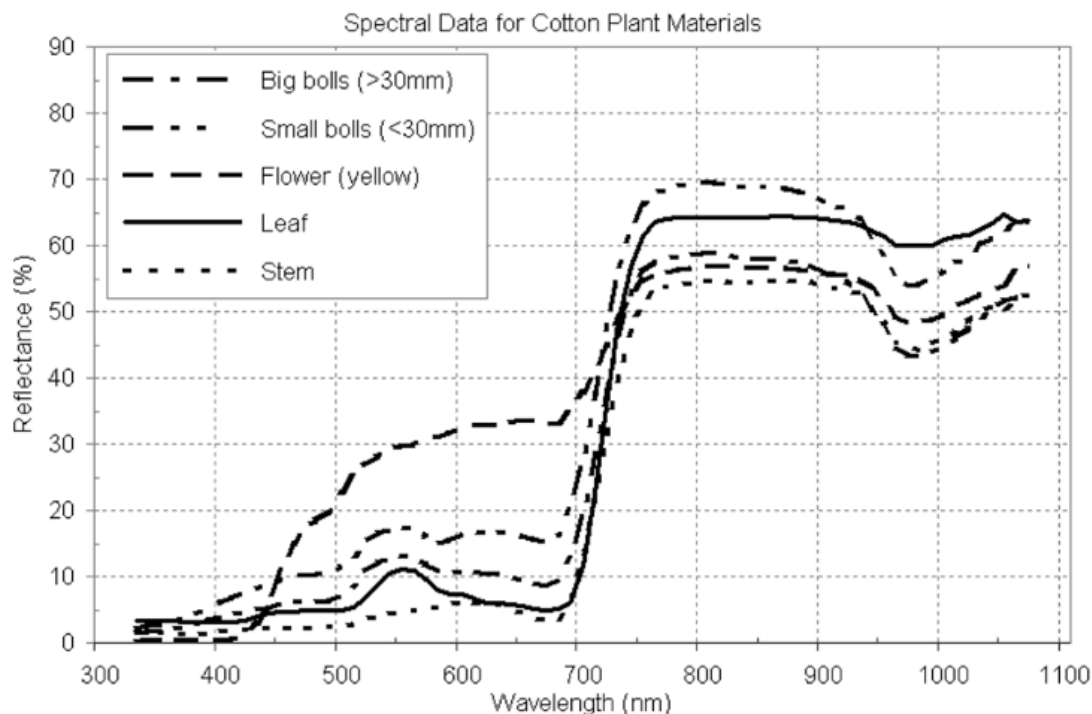
Research tools:

- Distance sensors to measure height and estimate leaf area index
- Image analysis of camera images to determine internode length, nitrogen status and plant size
- Multispectral properties using narrowband imaging

Spectral response of cotton structures



- Flowers could be distinguished from leaf material in red wavelengths 450-700 nm
- At 450-950 nm small bolls have highest reflectance but large bolls not distinguishable



Source: McCarthy, C (2009)
*Automatic non-destructive
dimensional measurement of
cotton plants in real-time by
machine vision.* PhD Thesis

Plant density



- Infrared filter increased contrast between leaves, soil, stubble

- Image analysis:

- **Identify potential plants**

1. Identify leaf (bright) pixels

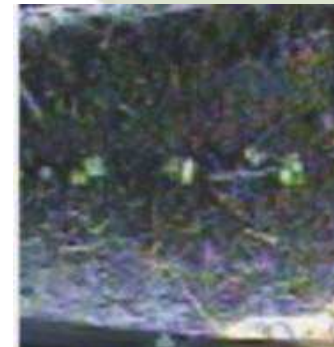
2. Assign each leaf pixel to a potential plant number index if connected to another leaf pixel

- **Size analysis**

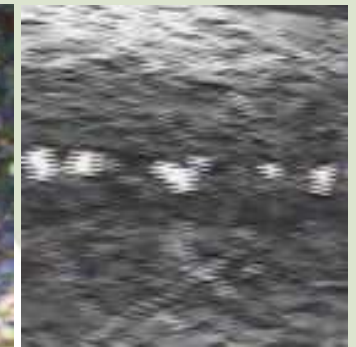
1. Count pixels in each potential plant identified

2. If count within threshold then a plant is detected and accumulate plant count

Visible:



Infrared:



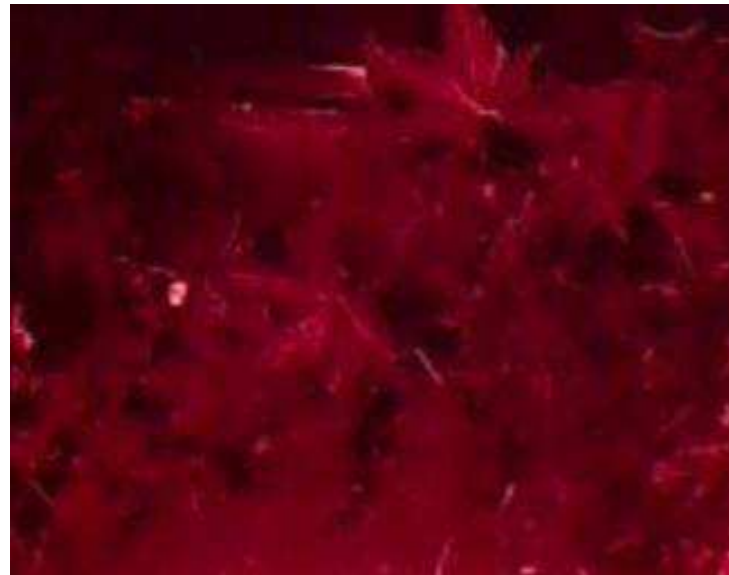
Square count

- Square spectral response is similar to leaves
- 21 days from first formation of pinhead square to white bloom, flowers last for 7 days
- Image analysis as for plant density but bright pixels are flowers

Visible:



Red only:



Boll count

- Boll shape can be distinguished from leaves
- Image analysis:
 - Identify potential bolls from brighter pixels
 - Shape analysis
 1. Count width and height of each potential boll
 2. If dimensions within thresholds then potential boll
 - Size analysis as for plants and flowers

Visible:



Infrared:



Platforms for surface irrigation



- Evaluated in the 2010/11, 2011/12 and 2012/13 cotton growing seasons

Ground-based platform for surface irrigation



Vehicle-based platform for surface irrigation



Irrigation machine mounted platform



- Evaluated in the 2012/13 cotton growing season

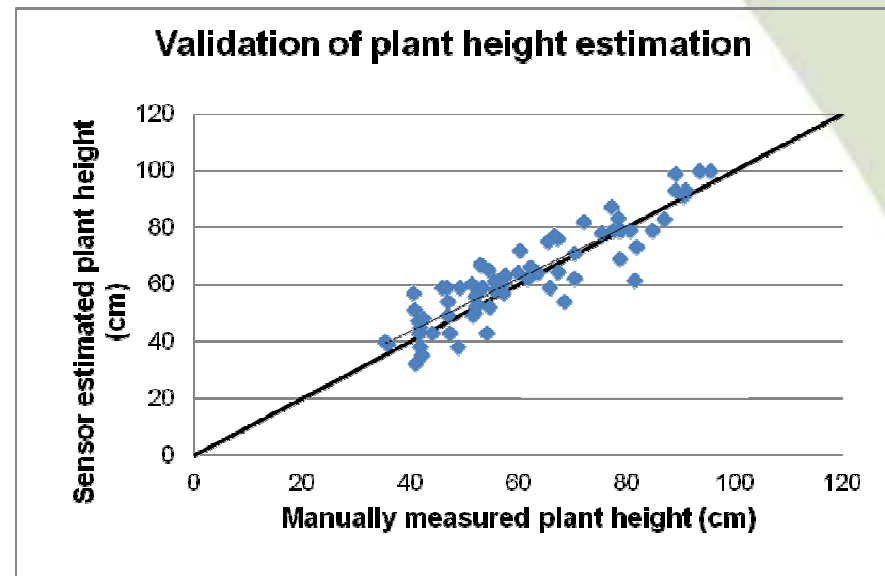
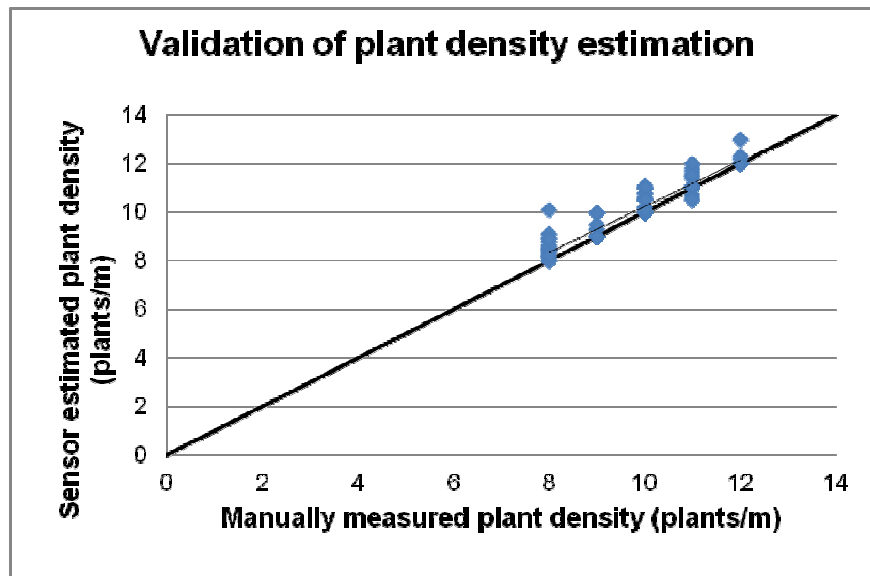
Overhead-mounted platform for centre pivots/lateral moves



Sensor validation – density and height



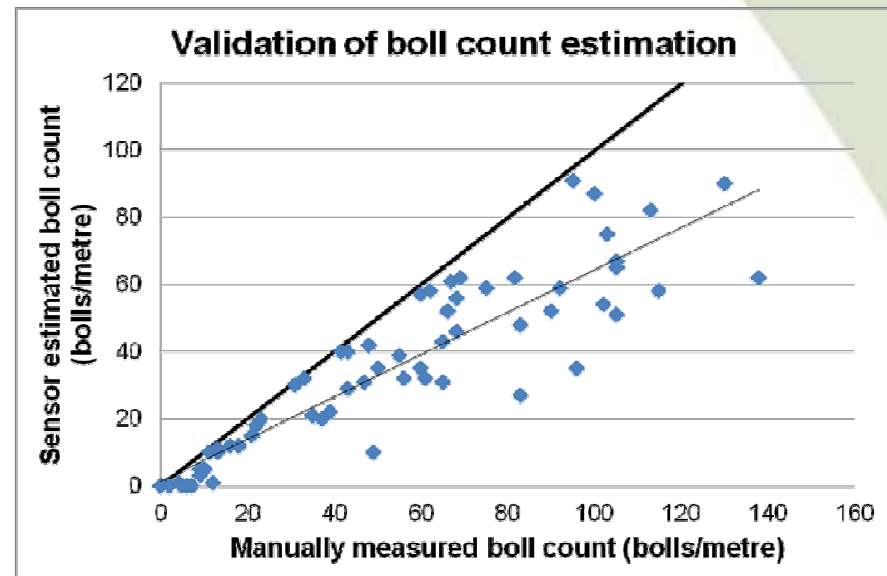
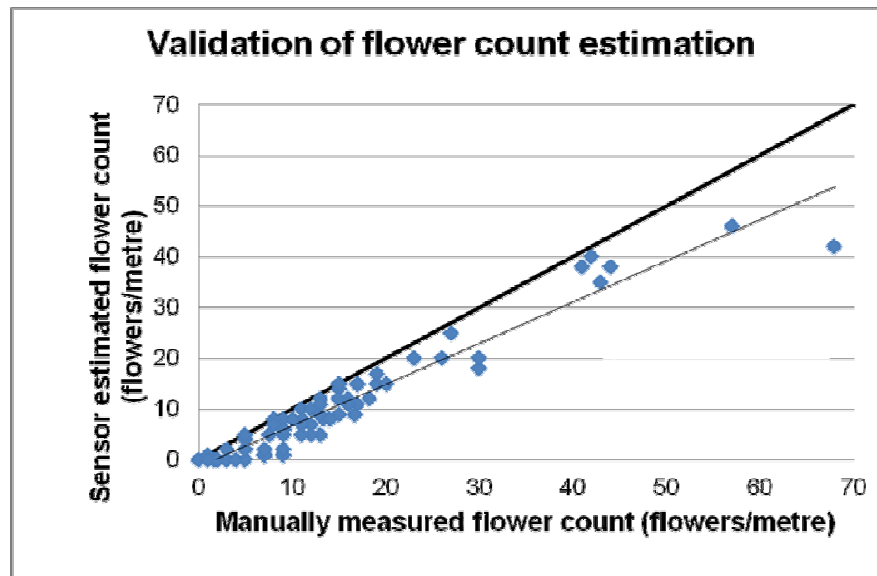
- Plant density generally overestimated from falsely identifying weeds or stubble in the image as small cotton plants
- Accuracy of distance sensor was ± 6 cm (± 4 cm in specification)



Sensor validation – flowers and bolls



- Underestimated flower count from occlusion by cotton leaves
- Boll count was underestimated because bolls lower on the plant were fully occluded in a top view of the crop



Conclusion



- Plant density and flower and boll count estimation was achieved with simple image analysis in red and infrared wavebands
- Plant height estimation using height sensors
- Sensing platform is suitable for on-the-go sensing of cotton plant parameters at high spatial resolution
- Additional side cameras required for improved boll detection

Potential use for estimating plant parameters in an automated irrigation system

Acknowledgements



- Cotton Research and Development Corporation
- Nigel Hopson and Lindsay Evans for providing field trial sites



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