

Reliability-Based Load Carrying Capacity Assessment of Bridges Using Structural Health Monitoring and Nonlinear Analysis

Shojaeddin Jamali¹, Tommy H.T. Chan¹, Andy Nguyen² and David P. Thambiratnam¹

¹School of Civil Engineering and Built Environment, Queensland University of Technology, Brisbane, QLD 4000, Australia.

²School of Civil Engineering & Surveying, University of Southern Queensland, Springfield Central, QLD 4300, Australia.

Abstract

For assessment of existing bridges, load rating is usually performed to assess the capacity against vehicular loading. Codified load rating can be conservative if the rating is not coupled with the field data or if simplifications are incorporated into assessment. Recent changes made to the Australian Bridge assessment code (AS 5100.7) distinguishes the difference between design and assessment requirements, and includes addition of structural health monitoring (SHM) for bridge assessment. However, very limited guidelines are provided regarding higher order assessment levels where more refined approaches are required to optimize the accuracy of the assessment. This paper proposes a multi-tier assessment procedure for capacity estimation of existing bridges using a combination of SHM techniques, advanced nonlinear analysis, and probabilistic approaches to effectively address the safety issues on aging bridges. Assessment of a box girder bridge was carried out according to the proposed multi-tier assessment, using data obtained from modal and destructive testing. Results of analysis at different assessment tiers showed that both load carrying capacity and safety index of the bridge vary significantly if current bridge information is used instead of as-designed bridge information. Findings emerged from this study demonstrated that accuracy of bridge assessment is significantly improved when SHM techniques along with reliability approaches and nonlinear finite element analysis are incorporated, which will have important implications that are relevant to both practitioners and asset managers.

Keywords

Load Carrying Capacity, Structural Health Monitoring, Reliability Analysis, Nonlinear Analysis, Box Girder

Introduction

Bridges are essential components of a road network that facilitate social connection and economic growth. In Australia, also known as ‘the Island Continent’, ground transportation is the major means of freight movement across states. More than 80% of the existing bridges are designed as per old design codes, while bridge codes in Australia have undergone major changes over the last three decades.¹ Recent version of the Australian Bridge Code (AS 5100.7) recognizes the disparities between bridge design requirements and assessment philosophy, with two added sections for bridge rehabilitation and timber bridges to address the sustainability concerns.²

In addition to the traditional vehicular loading test for bridge assessment, a section is added to assess the bridges using structural health monitoring (SHM) techniques such as damage detection and assessment, ambient testing and performance monitoring. However, the use of probabilistic models or reliability analysis is not addressed. Existing codified assessment procedure is deterministic in nature and only accounts for uncertainty in the assessment procedure by means of safety factors, e.g. live load and material factors. On the other hand, probabilistic approaches quantitatively take into account the uncertainties associated with the assessment procedure ranging from field testing to load rating, in which the reliability of the assessment procedure is qualitatively assessed enabling more transparency in the results and improved access to the bridge network.^{3,4}

In most of the international bridge codes, addition of real-life data into probabilistic approaches, e.g. SHM data collected over long-term monitoring, enables continuous refinement of the assessment procedure with actual information representing the current condition of the bridge, also known as ‘as-is’ bridge condition.^{5,6,7}

Considering significant changes made to the Australian bridge code and existing old bridge network with increasing vehicular loadings, it is inevitable to have an accurate and well-defined assessment procedure for aging bridges. Although use of proof load testing and SHM is permitted by the revised code, no specific guideline is provided regarding details and implementation of higher tiered assessment levels. To address this issue, this paper proposes a practical framework for holistic assessment of existing bridges by using higher tiered analysis and SHM techniques, and systematically evaluates its effectiveness for bridge capacity assessment. Also, a relationship between load rating and reliability index is developed, and the feasibility of a reliability-oriented assessment, which is not covered by the revised code, is critically investigated.

A box girder bridge laboratory model is assessed for its ultimate load carrying capacity (LCC) using the proposed multi-tier assessment procedure for validation and comparison with existing codified assessment methods. What follows are detailed components of the bridge assessment using the proposed multi-tier assessment framework commencing from pre-test preparation to post-test diagnosis, in order to provide a comprehensive procedure for real-life implication.

Multi-tier Assessment Procedure

The basic premise of load rating is that the minimum strength capacity of the bridge should be greater than the maximum load effects due to external loading. Rating is performed at critical components of the bridge for various capacity checks, e.g. flexural capacity; with the lowest rating determined being the load rating factor of the whole bridge for the nominated rating vehicle.

Despite the importance of the probabilistic approaches for bridge assessment that have been adopted by other international bridge codes, no specific provision is available within the recent Australian bridge code as a means of refined analysis.^{7,8} For target level of safety, reference is made to AS/ISO 13822⁹ and AS 5104¹⁰, which are reproduced as an extended version of the international standard ISO 2394¹¹.

In the reliability context, a limit state function (LSF) is defined as the boundary between safety and failure region. Considering the resistance of a bridge as R and the external loading as Q , the corresponding LSF is written as $g = R - Q$; so the probability of failure (P_f) is defined as $R < Q$, and the corresponding reliability index (β) is calculated as shown in equation (1).

$$\beta = \Phi^{-1}(P_f) \quad \text{or} \quad P_f = \Phi(\beta) \quad (1)$$

In above equation, Φ is the inverse of cumulative distribution function for the LSF under consideration. A structure is considered safe when $g > 0$, else it becomes unsafe. The extent to which reliability is incorporated into analysis is based on the degree of the probability involved, ranging from deterministic to fully probabilistic approaches.¹²

First-order and second-order reliability methods are the simplest and most commonly used methods that apply the first two terms of Taylor series expansion to approximate the LSF.^{3,13} For large structures, LSF might not be linear and obtaining a closed-form solution is very cumbersome if not impossible. In order to have an accurate procedure with reasonable computational time, Rackwitz-Fiessler procedure¹⁴ and Markov Chain Monte Carlo (MCMC) method¹⁵ are adopted for this study. Rackwitz-Fiessler procedure is an iterative procedure that applies to linear and nonlinear LSF taking into account the distribution of random variables. This procedure is ideal for simple LSF as it requires very few iterations to reach convergence. On the other hand, MCMC is suitable for complex LSF involving nonlinear models, in which a closed-form solution can be estimated.

In probabilistic methods, each random variable is represented by its statistical parameters like coefficient of variation (CoV) and Bias (i.e. ratio of mean to nominal value). These statistical parameters are representative of deterministic values that reflect the uncertainty inherited in each of the load and resistance parameters. Reliability of statistical parameters mainly depends on the sample size, i.e. higher sampling rate covers more uncertainty range and thus results in more realistic statistical data

Previous investigation of adopting US data for calibration of Australian code for concrete structures (AS 3600), which is a relatively similar standard to bridge design code (AS 5100.5), showed very identical results between statistical parameters of AS3600 and ACI

318.¹⁶ The variety of bridges considered in the literature for probabilistic modelling of the bridges were diverse enough to be assumed for other cases.

In this study, due to lack of complete statistical database for Australian bridges, LSF functions are formulated based on the statistical parameters as displayed in Table 1, which are the result of extensive investigations carried out collectively for calibration of AASHTO LRFD and ACI. For correlation of the random variables to each other, depending on their relationship in the LSF, correlation coefficients (viz, linearly or nonlinearly correlated) for estimation of the ultimate LCC. Similarly for other LSF such as SLS assessment, random parameters and their corresponding statistical data and correlation can be defined.

Table 1. Statistical parameters of random variables

Parameter	Notation	Bias	CoV	Distribution	Reference
Dead Load					Nowak ¹⁷
Factory made	DL	1.03	0.08	Normal	
Cast-in place		1.05	0.10		
Deck wearing surface		1.00	0.25		
Live load with impact factor	LL	1.15	0.18	Extreme Type I	Nowak ¹⁷
RC Resistance		1.128 [†]	0.135 ¹		Nowak ¹⁷
Moment	R	1.14	0.13	Lognormal	
Shear		1.20	0.155		
Area of steel reinforcement	A_{st}	1.0	0.015	Normal	Nowak and Szerszen ¹⁸
Steel yield stress	F_y	1.05	0.11	Lognormal	Ellingwood ¹⁹
Effective depth of steel	d_i	1.0	0.075	Normal	Miraz and MacGregor ²⁰
Concrete compressive stress	F_c	0.94	0.33	Lognormal	This study
Concrete area	A_c	1.0	0.04	Normal	Nowak and Szerszen ¹⁸
Neutral axis	NA	0.89	0.14	Normal	This study
Capacity reduction factor	ϕ	0.97	0.05	Normal	This study
Stress block depth	γ	0.84	0.27	Normal	This study
Coefficient of equivalent rectangular stress blocks	α	0.84	0.27	Normal	This study
RC effective depth	d_o	0.99	0.04	Normal	Ellingwood ¹⁹
Width of beam, cast-in place	b_w	1.01	0.04	Normal	Ellingwood ¹⁹

[†] Including material, fabrication and analysis factors

Ultimate limit state (ULS) condition for bridge load rating is defined in equation (2), so the LSF can be stated as the condition when the capacity is lesser than the combination of other load effects.

$$\phi R \geq \gamma_{DL} DL + \gamma_{SDL} SDL + \gamma_{LL} LL(1 + DLA) \quad \therefore \text{ULS} \quad \begin{matrix} \square \\ \square \\ \square \end{matrix} \quad \text{RF}$$

$$g(R, DL, SDL, LL) = R - (DL + SDL) - LL \quad \therefore \text{LSF} \quad \begin{matrix} \square \\ \square \\ \square \end{matrix} \quad \text{RI}$$

where:

(2)

R is the resistance with ϕ capacity reduction factor, DL is the dead load,

SDL is the superimposed dead load, LL is the live load,

DLA is the dynamic load allowance and γ are the load factors

It can be stated from equation (2) that the reliability index (RI) can be expressed for various ULS conditions as required for RF, denoting that RF and RI are mutually related.

Visual inspection or proof load testing require investment in terms of preparing the loading vehicle, personnel, traffic control, time management and monetary issues. It is basically a trade-off between the quantity of information needed and the potential risk of damaging the bridge components during testing. By using SHM techniques and measuring the response of the bridge in-operation, numerical model of the bridge is updated to match the as-is condition of the bridge.

Therefore, a ‘virtual load test’ can be conducted on the calibrated analytical model to estimate the ultimate LCC and gain more in-depth understanding of the bridge response and failure modes. ‘As shown in Figure 1, structural and modal properties of the bridge are updated using in-service data obtained by SHM techniques, after which nonlinear material properties are defined. Vehicular loading, permit vehicle or other types of live loadings can be defined as the failure live load, since live loading is considered as the most significant parameter affecting the bridge capacity.’²¹

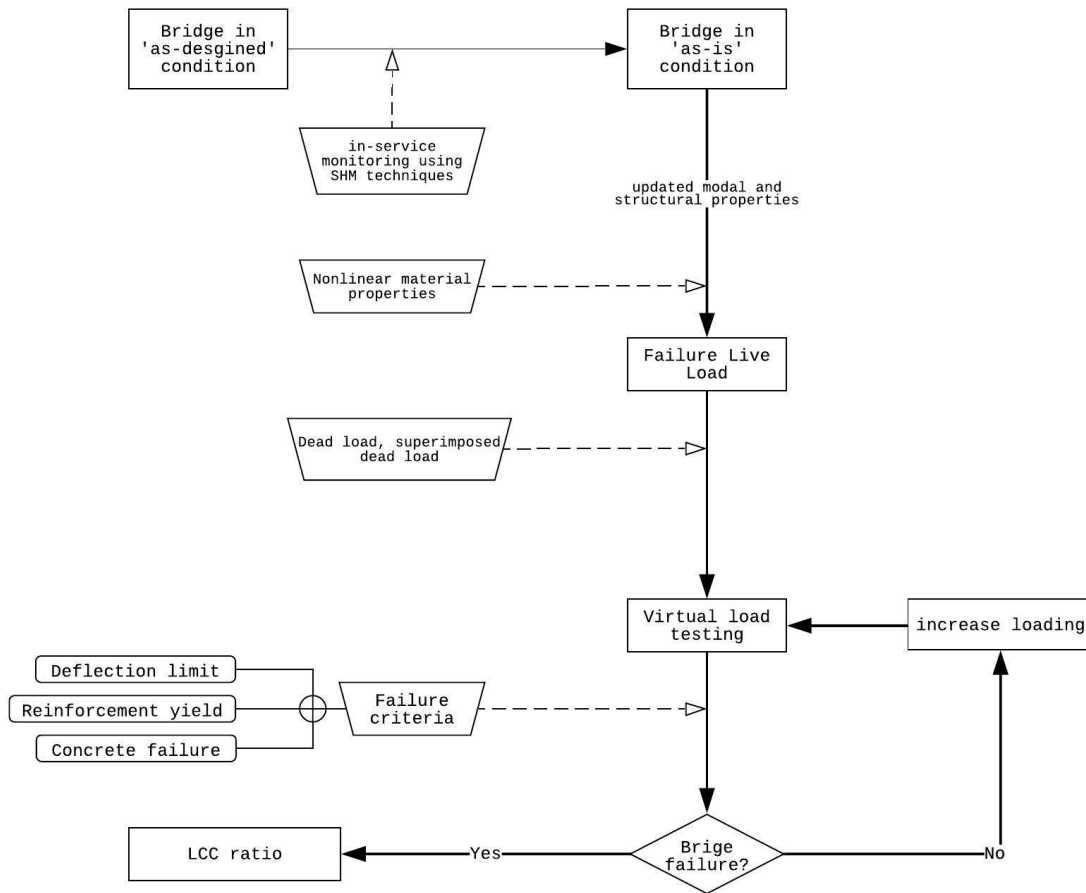


Figure 1. Process of LCC estimation

The failure load is increased until the bridge fails under the defined failure criteria, such as deflection limit, yield of steel reinforcement, or concrete failure (tension or compression). Then, LCC ratio is determined in terms of ultimate failure load to the bridge permanent loads as shown in equation (3). Permanent bridge loads refer to the bridge mass and superimposed dead loads (if significant). Higher LCC ratio implies that higher loading is needed to reach the failure criteria.

$$LCC_{ratio} = \frac{\text{Ultimate Failure Load}}{\text{Bridge Permanent Loads}} \quad (3)$$

Estimated LCC in equation (3) is in fact the true ultimate LCC of a bridge for the specified failure load, using existing bridge condition, whereas RF is the LCC of the bridge considering all of the codified load factors including DLA.

The proposed holistic multi-tier assessment procedure is illustrated in Figure 2. In this assessment procedure, as the accuracy of evaluation increases in higher tiered approaches, so does the cost and the safety of the structure. Safety refers to the degree of accuracy and reliability in the assessment, while cost refers to the fiscal policy, computational time and workload. This multi-tier assessment procedure considers currently implemented methods for bridge LCC assessment in Australia, and proposes two additional assessment tiers, viz. Tier 3 for in-service assessment using SHM techniques, and Tier 4 for reliability analysis which is not covered by the bridge code.

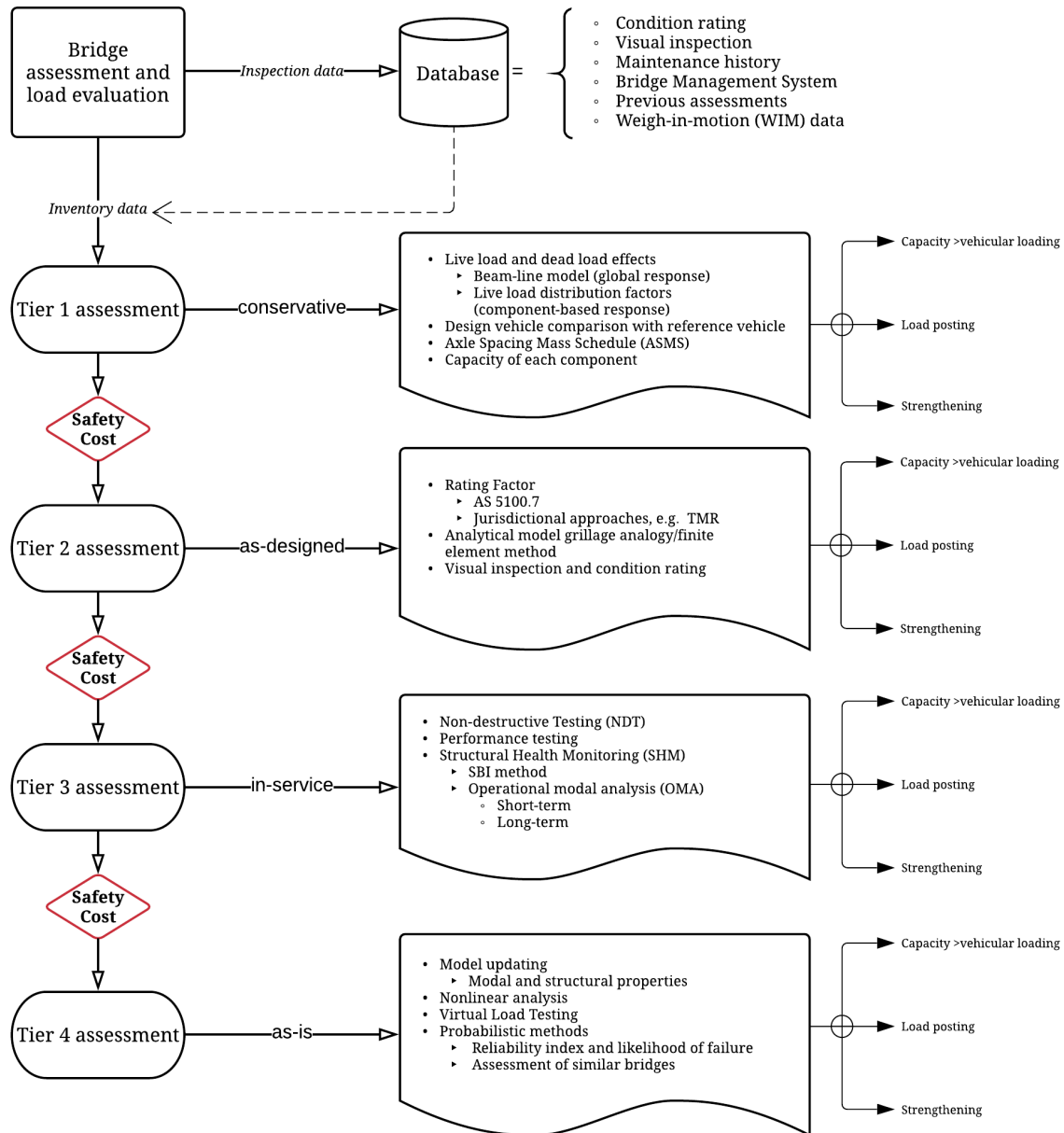


Figure 2. Multi-tier assessment procedure for evaluation of existing bridges

Tier 1 assessment is the most basic tier and usually serves as the first-pass check, which includes carrying out Axle Spacing Mass Schedule (ASMS) approach or simple beam-line analysis of the bridge compared against design loading with or without live load distribution factors.^{5,22} These approaches are considered as ‘one size fits all’, which means ratings will be very conservative. This tier determines if further assessment is required and whether or not the bridge has sufficient capacity for the nominated vehicular loading.

Tier 2 assessment is basically the codified approach, whereby as-built capacity is checked against existing design code and vehicular loading using linear analysis analytical model, viz. grillage model or finite element model. Most of the existing bridges in Australia are currently assessed in this tier including jurisdictional approaches. Ratings are based on theoretical capacity using information from designed condition or previous assessment.

In Tier 3, the existing condition of the bridge is considered by collecting data from non-destructive testing or ambient vibration testing using SHM techniques such as operational modal analysis (OMA), as well as other means of in-service assessment like SBI method for quick on-site estimation of bridge stiffness and capacity.²³ In-service monitoring could be short or long-term, and it includes any data related to the performance of the bridge such as deflection due to traffic. The objective of in-service monitoring is largely dependent on the results of previous tiers, in which the appropriate monitoring plan is arranged to study the specific response of the bridge over time.

In Tier 4 assessment which is using as-is bridge information, structural system identification and numerical model calibration are carried out. Calibrated structural, material and modal properties of the bridge are used for capacity assessment using virtual load testing for various loading conditions. Estimated capacities are assessed by using reliability analysis, and the uncertainties associated with any stage of assessment are evaluated by using probabilistic methods. Results of Tier 4 assessment are more accurate and reliable compared to conventional approaches (Tiers 1 and 2), since estimated LCC reflects the actual bridge capacity by considering existing bridge condition, and the accuracy of assessment is validated by reliability analysis.

Another merit of the multi-tier assessment procedure is that the response of the bridge can be assessed at component-based or as system-based. At component-level, the response of the individual component is assessed, e.g. main longitudinal girder. While at system-level, the interaction of all components contributing to the overall capacity is considered, e.g. result of virtual load test is a system-level response.

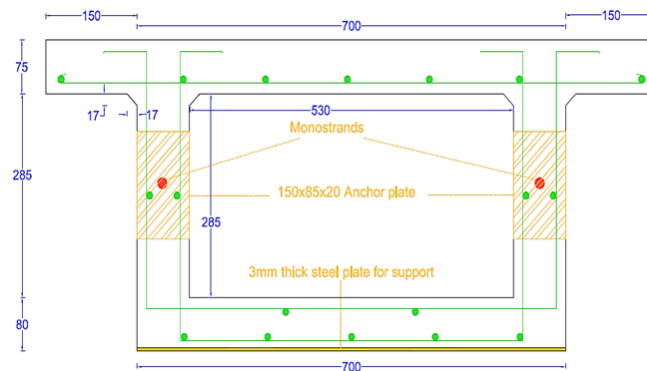
In each assessment tier, appropriate decisions are made regarding the remaining service life of the bridge. Load limitation, strengthening and permit access are common bridge management plans by asset owners.²⁴ Such procedure is applicable to bridge superstructure and substructure for various limit state conditions.

Description of the Test Structure

In order to verify the proposed methodology for LCC assessment, a single-cell prestressed reinforced concrete Box Girder bridge laboratory model was studied. The laboratory model is a scaled down version of the common cellular bridge decks currently operational in Australia. As shown in Figure 3, the reinforcements are distributed longitudinally and transversely.



(a)



(b)

Figure 3. Box Girder Bridge, a) in testing condition, b) dimensions in mm

Initially, the bridge was tested in November 2016 for identification of prestressed force at three different levels of post-tensioning located through mid-web. Detailed description of the construction procedure and prestress force identifications are described elsewhere.²⁵ The tendons were removed from the ducts and, after a period of one year, the Box Girder was re-set up. All these were supposed to cause certain changes in physical, structural and material properties. Hence the purpose of testing was to assess the existing condition of the bridge considering all of the changes using the proposed multi-tier assessment procedure.

Development of Modelling Technique

In the proposed multi-tier assessment, different modelling techniques are required. In this section, efficient modelling procedure for the purpose of model updating and virtual load testing are described. Three different numerical models of the Box Girder are developed, viz. grillage analogy (GA) model for Tier 1 and Tier 2 assessments, linear finite element (FE) model for Tier 3, and Nonlinear FE (NLFE) model for Tier 4 assessment (see Figure 4). GA model is the simplified model that is easy to interpret the results, while linear FE model is considered as the design level, since such model is used by bridge practitioners for design and assessment. NLFE model incorporates all of the physical details which are ignored in the previous models, e.g. inclusion of reinforcement and concrete-steel interaction. In case of limited information on bridge geometry such as old bridges with incomplete design drawings, on-site measurement can be performed to estimate the geometric measure of bridge components. Process of numerical model creations, with advantages and limitations of each modelling technique is detailed in the authors' previous works.^{22,23,26}

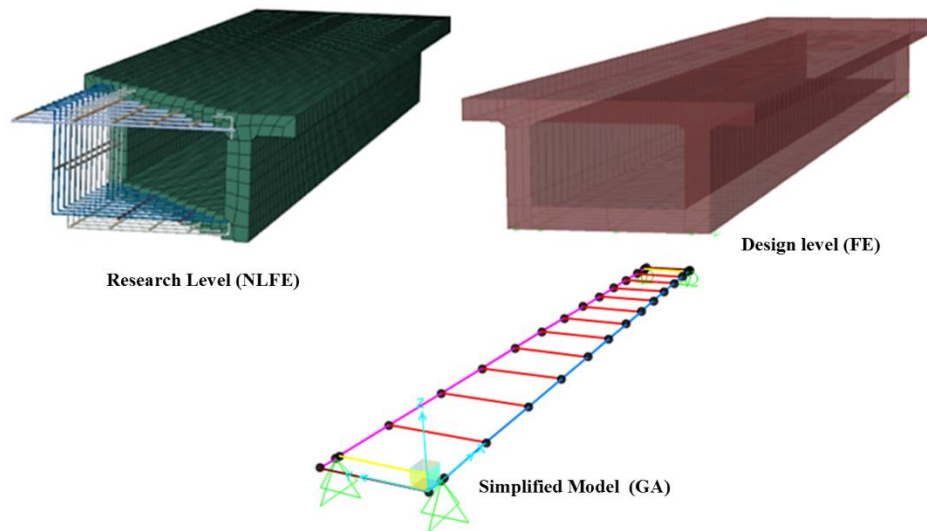


Figure 4. Developed numerical models: FE and GA are modelled in CSiBridge[®], and NLFE modelled in Abaqus[®]

The hidden reserved capacity of the bridge is masked if the numerical model is not calibrated with existing bridge information. Nonlinear analysis can be carried out on the calibrated numerical model of the bridge using information gained from SHM data.

To capture the nonlinear response of the Box Girder, concrete damage plasticity (CDP) model is used, which accounts for compressive crushing and tensile cracking of the concrete. This model is based on the damage mechanics and flow theory of the plasticity, which has been extensively used to study the nonlinear behavior of the concrete structures.²⁷⁻²⁹ In CDP model, damage is represented by the post-peak response of the constitutive concrete model in uniaxial compression and uniaxial tension.

There are many concrete models available in the literature, and the main difference among them are the post-yield behavior and the number of inputs required to construct the material model. For compressive behavior, the model proposed by Attard and Setunge³⁰ is selected due to the fact that only compressive stress is required as the input, and the post-yield response of concrete is well developed with applicability to a broad range of in-situ concrete. For nonlinear tensile behavior, the model developed by Gopalaratnam and Shah³¹ is adopted, which has smooth convergence in the tension stiffening zone that alleviates the convergence issues. Other concrete models may be used provided that accurate inputs for constructing the constitutive material curve are available. For steel reinforcement, bilinear model having an elastic perfectly-plastic relationship is considered. Other sophisticated steel constitutive models such as trilinear model can be used as well, provided that the exact information regarding reinforcement details and nonlinear parameters are available.

An experimental four-point bending test selected from literature was simulated to validate the material models for reinforced concrete structures.³² Numerical simulations showed that LCC estimated by virtual load testing is in good agreement with the experimental capacity, in which the deflection at the end of loading was 8.5 mm with steel yielding as the mode of failure in the mid-region, which are in agreement with previous study.³³ This denotes that the defined material models can estimate the nonlinear response of the Box Girder under failure live load.

Modal and Destructive Testing

During construction of the Box Girder, steel plates were embedded into the concrete surface for easier sensor installation, and these locations were used for sensor positioning. Criteria for choosing proper sensor layout include the objective of the testing, available number/type of sensors, excitation location, and maximum modal displacement points.^{1,34} Figure 5 shows three examples of sensor positioning layouts that were used for modal testing, in which each arrow corresponds to a single sensor in that direction, which was used for measuring acceleration. An advantage of having more than a single sensor layout is that one can crosscheck the quality of collected data across each measurement, and to ensure that true structural modes are captured. For each modal test, vibration signature of the Box Girder was recorded due to random and impact hammer excitation using data acquisition system. Recorded measurements were post-processed on-site using frequency-domain and time-domain modal estimation techniques, e.g. enhanced frequency domain decomposition and stochastic subspace identification methods. For each set of measurement, signal processing produced similar results, indicating that sensor layouts successfully detected real modal parameters.

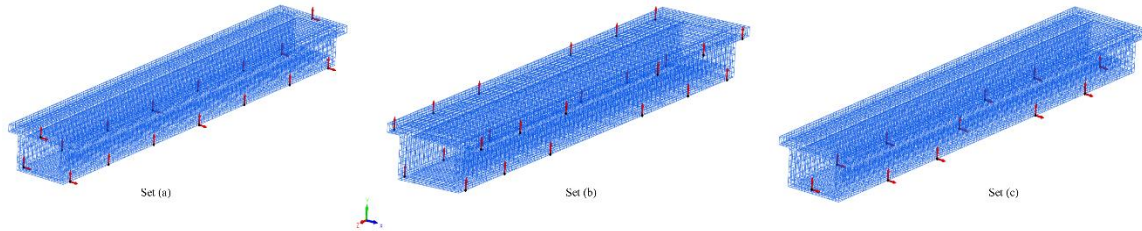


Figure 5. Examples of sensor placement layouts used for OMA

Destructive testing of Box Girder was performed with twofold objectives: to find out the ultimate LCC and to validate the results of Tier 4 assessment, i.e. virtual load testing. As shown in Figure 6, the rigid beam acts as load-transfer and is placed on two steel supports seated on top of the webs, while load cell acts as live load. This prevents the punching shear failure through top slab by transferring the load into webs, which is similar to the design axle loading (A160) in AS 5100.2 that acts as failure load for estimation of the ultimate LCC. The boundary conditions represent ideal pin-rollers that were seated on a stiff beam anchored to the ground to prevent any movement. Load rate of 0.01 mm/s was applied to the load cell using displacement-control approach.

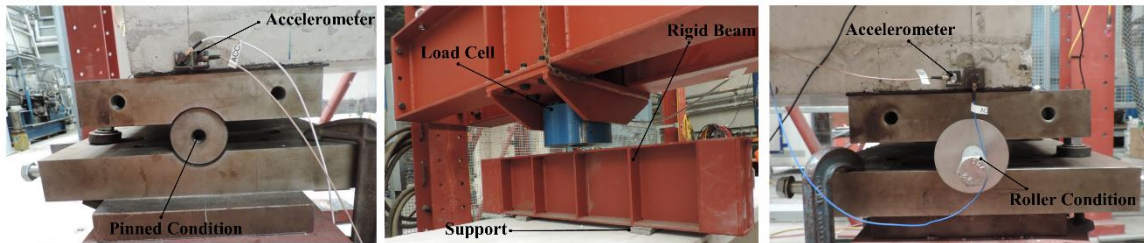


Figure 6. Destructive testing setup

Numerical Model Calibration

In this study, model calibration is divided into three stages, viz. correlation analysis, sensitivity analysis and model updating.³⁵

In correlation analysis, experimental and numerical degrees of freedom (DOF) are correlated; which assist in mode shape identification and interpolation of missing DOF's.

The effect of different parameters on modal properties are investigated using sensitivity analysis. Parameters included are stiffness of the boundary conditions, concrete and steel reinforcement material properties. Any other variable that has the potential to be considered; however, irrelevant parameters may lead to an updated but physically meaningless model.

Due to the fact that construction process of the Box Girder was completed in three separate stages, Box Girder was grouped into three sections which are web, soffit and top slab. The results of the sensitivity analysis can be compared in Figure 7, in which response 1–4 are the first four natural frequencies of the Box Girder, and parameters 1–10 are listed accordingly. Responses and parameters for the model updating were selected based on the preliminary parametric study to investigate the effect of change in the updated parameters due to the variation in the responses.³⁶ Referring to the color code for rate of changes in each response, it is apparent from the rate of fluctuation that each experimental response has a different effect on the corresponding parameter. For example, for first experimental response, Young’s modulus (E) has an increasing trend, while material density (ρ) is decreasing. Effect of stiffness from boundary conditions (KX and KY) is marginal on experimental frequencies, which indicates that it is not a very sensitive parameter for model updating in the case of Box Girder. Main effects in sensitivity analysis are due to concrete and steel material properties, which are considered as primarily parameters for model updating.

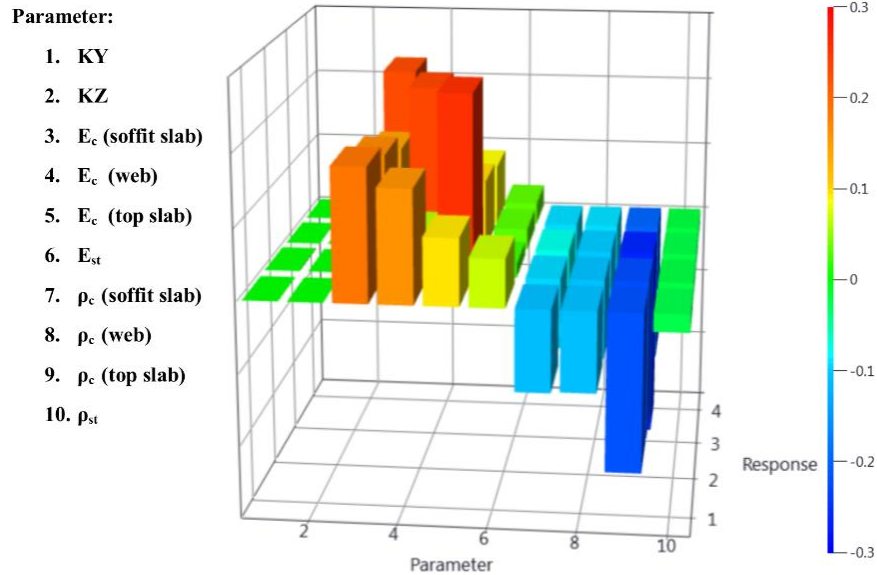


Figure 7. Sensitivity analysis

On selection of updating parameters, model updating is conducted using differential methods. CCMEAN is the correlation coefficient of weighted absolute relative differences between updated and experimental frequencies; while CCMABS is the absolute relative difference of CCMEAN.³⁷ These correlation coefficients as shown in equation (4) and are used to show the level of agreement between experimental modal parameters and the corresponding analytical parameters.

N is the number of selected experimental frequencies, f is the natural frequency and C_R is the response confidence. Perfect correlation indicates no difference between experimental modal parameters and their analytical counterparts, therefore representing the bridge in as-is condition.

$$\text{Correlation Coefficient} = \frac{1}{C_R} \sum_{i=1}^N C_{R_i} \frac{\Delta f_i}{f_i} \quad \text{where} \quad C_R = \sum_{i=1}^N C_{R_i} \quad (4)$$

The graph in Figure 8 shows the convergence process during model updating. CCMEAN is the correlation coefficient of weighted absolute relative differences between updated and experimental resonance frequencies; while CCMABS is the absolute relative difference of CCMEAN. For perfect correlation, the correlation coefficients should be all zero which is the case for the Box Girder. Also, very few number of iterations indicates that model updating is successful with minimal computational time.

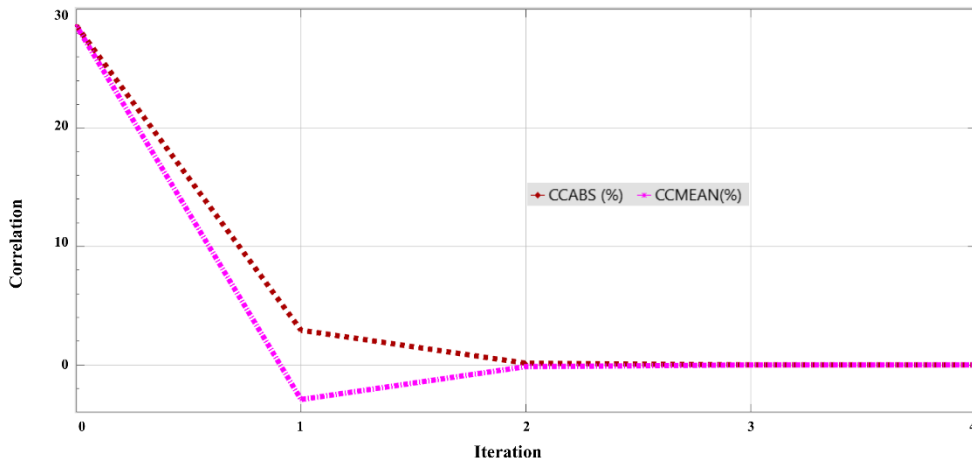


Figure 8. Convergence of the model updating

The results obtained from model updating are summarized in Table 2, and calibrated mode shapes of Box Girder are presented in Figure 9.

Table 2. Parameters before and after model updating

Parameter	Before Updating (as-designed) ‡	After Updating (as-is) ¥	
Frequency (Hz)	<i>1st mode</i>	22.9 (VB) †	18.9 (VB)
	<i>2nd mode</i>	43.4 (LB)	60.8 (T)
	<i>3rd mode</i>	57.2 (LS)	63.3 (VB)
	<i>4th mode</i>	61.4 (LB)	73.5 (LS)
E (GPa)	<i>Soffit slab</i>	32	15.7
	<i>Web</i>	32	27.3
	<i>Top slab</i>	32	18.1
	<i>Reinforcement</i>	200	199.8
ρ (kg/m³)	<i>Soffit slab</i>	2400	2425
	<i>Web</i>	2400	2420
	<i>Top slab</i>	2400	2434
	<i>Reinforcement</i>	7850	7863
K (x10⁸ N/m)	<i>Longitudinal</i>	assumed full stiffness	99.99
	<i>Vertical</i>	assumed full stiffness	100

‡ Box Girder after construction with posttensioning (November 2016)

¥ Box Girder without posttensioning (November 2017)

† VB: vertical bending, LB: lateral bending, LS: lateral sway, T: torsional

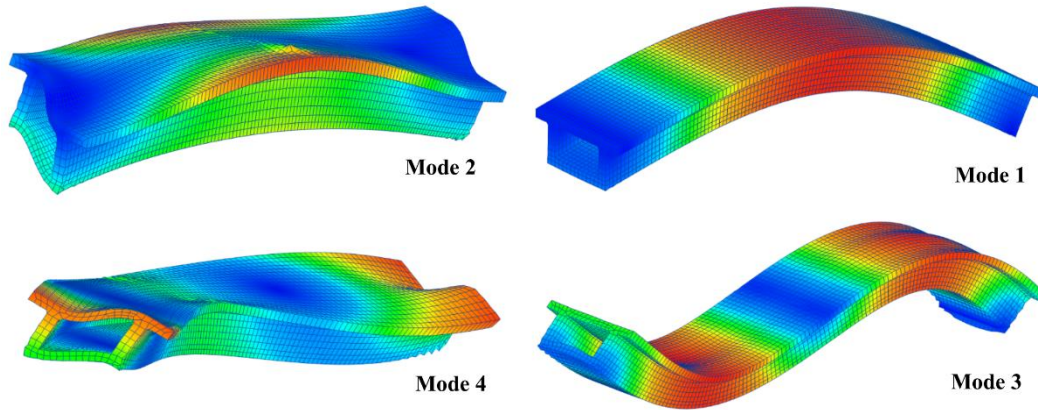


Figure 9. Mode shapes of Box Girder

Sound engineering judgment and past experience are two important factors to verify the accuracy of updated parameters, otherwise updating parameters are forcefully changed during updating process to match the experimental responses.

Referring to

Table 2, modal and structural properties of the Box Girder are changed notably. Values before updating are as-designed conditions and modal parameters are for posttensioning with different boundary conditions. Whereas after updating parameters are as-is condition of the Box Girder. The first four frequencies obtained from modal testing are 18.9, 54.2, 64 and 80.7 Hz respectively. Difference in the modal parameters can be explained by the fact that Box Girder has no posttensioning tendon, and its boundary conditions were changed leading to different new modes, especially higher order modes that are coupled in nature. The observed change in material properties can also be partially attributed to the presence of some cracks, which existed in the Box Girder at the soffit slab. These cracks further propagated during destructive testing, which are explained in the next section.

Load Carrying Capacity Assessment

For the purpose of comparison, LCC assessment is carried out using traditional-based approach (Tier 2), and using proposed virtual load testing (Tier 4). Tier 1 assessment is excluded due to its simplicity.

LCC ratio

Figure 10 shows the ultimate LCC of the Box Girder obtained by destructive testing and virtual load testing. For virtual load testing, three curves represent the load-deflection for different contact coefficients between the load cell and the surface of the Box Girder during loading phase. Referring to load-deflection curve, virtual load testing on updated FE model

produced similar results to that of experimental curve; considering the fact that all material and structural properties were back-calculated using SHM techniques, e.g. using

Table 2. Parameter d_t in Figure 11 illustrates the extent of tensile damage in affected concrete zones, values closer to unity indicates higher tensile failure and in turn more cracks. Propagation of cracks in the virtual load testing follows similar trend to that of actual testing, where cracks are developed throughout the bridge width and stretched up to top slab at mid-span. For localized information on damage, existing methods for damage assessment can be applied to the updated model.³⁸

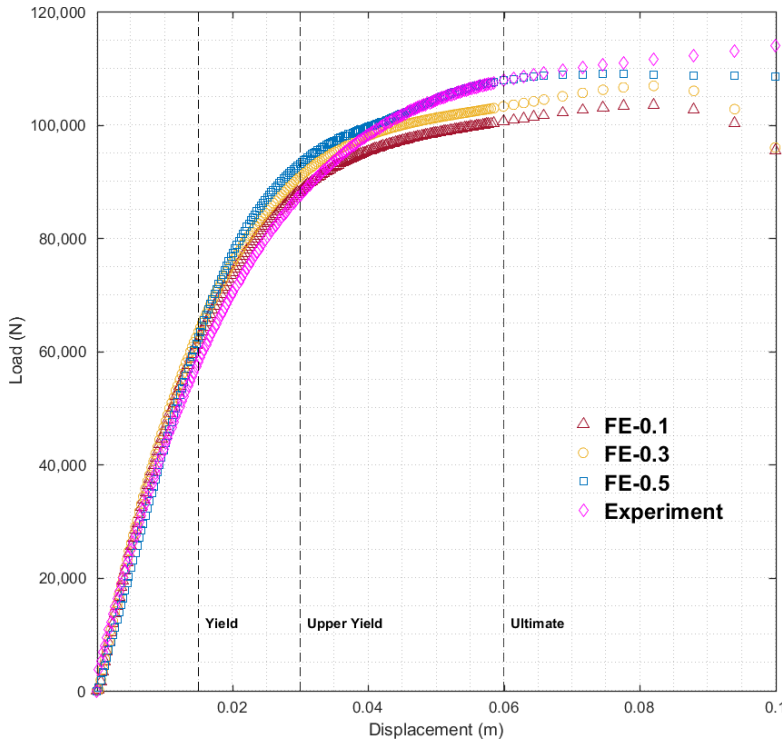


Figure 10. Load-deflection curve of the Box Girder

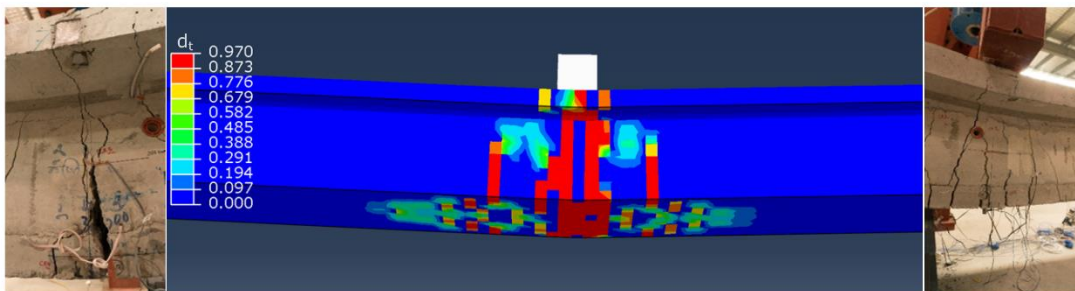


Figure 11. Crack patterns in destructive testing and virtual load testing

Failure of Box Girder was divided into three stages, viz. yield, upper yield and ultimate stage. Referring to Figure 10, at yield stage when the failure load is 58kN, the bridge enters post-elastic range and appearance of hair-line cracks become visible with bare eyes; while

at upper yield stage, the failure load increases to 87.5 kN, in which cracks propagate further by increasing in dimension and extending to the non-loaded regions. Ultimate stage is defined as the failure of the bridge which makes it dysfunctional for service. When the failure load reaches 108 kN, the concrete at bottom of mid-span falls off and yield of steel reinforcement is clearly visible, and hence the virtual load test discontinued. Because of the symmetry, load distribution by each web is similar and hence substantial load redistribution occurs before ultimate stage is reached. Having verified the validity of virtual load testing against destructive testing, calibrated FE model is used for shear failure. Using equation (3), the LCC ratio of the bridge is as follows: 6.48 for ultimate flexural capacity and 12.3 for ultimate shear capacity, which indicates that Box Girder has higher resistance to shear failure. Since LCC ratio considers the actual condition of the bridge using updated structural and material properties, no load factor is applied to equation (3). Analytical model for virtual load testing needs to be made once, and it can be reused and updated for preparation of field test, identification of possible failure modes, changes in configuration of as-of-right vehicles and assessment after extreme events.

Rating Factor

Load rating was carried out for bending moment (M) and shear force (V) under two vehicular loadings: A160 as axle load representing the load cell, and T44 representing the previous major design vehicle.²⁵ These vehicular loadings were scaled down by a factor of 10, in order to be applicable to the Box Girder carriageway. As can be seen from Table 3 with reference to relative percentage difference (RPD), ultimate LCC of the Box Girder is changed significantly prior (Tiers 1 and 2) and after considering as-is condition (Tiers 3 and 4). For example, using as-designed condition, flexural capacity is capable of carrying 2.47 tons under A160 loading, while this value drops to 1.84

Table 3. Rating factors at ULS

ULS		A160 (10%)			T44 (10%)		
		as-designed	as-is	RPD (%)*	as-designed	as-is	RPD (%)
M	RF	1.51	1.12	26	1.54	1.15	25
	RF in Tons	2.47	1.84		6.78	5.1	
V	RF	3.87	3.22	17	3.46	2.90	16
	RF in Tons	6.4	5.3		15.2	12.8	

$$* \text{Relative Percentage Difference (RPD)} = \frac{\text{Rating}_{\text{as-designed}} - \text{Rating}_{\text{as-is}}}{\text{Rating}_{\text{as-designed}}} \times 100$$

This can be explained by the fact that Box Girder had higher flexural resistance with prestressing force in the 15.4mm tendon located in each web, but after removal of tendons; the bearing capacity of the Box Girder relied entirely on concrete strength and steel reinforcement. As the result, neutral axis of the whole Box Girder shifted upward, which made larger portion of Box Girder to be in the tension zone. On the other hand, shear force resistance that has better ratings in all cases, which is due to the posttensioning applied at each web. From the principle of stress flow, the maximum shear stress occurs in the mid-height of web; which is the place that high prestress force was induced.

Taken together, these results highlight the positive aspects of using multi-tier assessment procedure that considers as-is condition for bridge load rating.

Reliability Analysis

All of the previous assessment results are deterministic and do not consider the uncertainty of the parameters, for example uncertainties in material properties. To account for uncertainty involved, reliability analysis is performed as a part of Tier 4 assessment to further validate the information obtained from previous assessment tiers.

Table 4. Reliability Index at ULS

ULS	A160 (10%)		T44 (10%)	
	M	V	M	V
as-designed	$\beta = 2.196$	$\beta = 6.25$	$\beta = 2.354$	$\beta = 5.69$
	$P_f = 0.0140$	$P_f = 2.0261 \times 10^{-10}$	$P_f = 0.0093$	$P_f = 6.97 \times 10^{-9}$
as-is	$\beta = 0.7710$	$\beta = 5.73$	$\beta = 0.939$	$\beta = 5.181$
	$P_f = 0.2204$	$P_f = 5.1413 \times 10^{-9}$	$P_f = 0.1739$	$P_f = 1.1035 \times 10^{-7}$

The results shown in Table 4 are obtained by Rackwitz-Fiessler method as semi-probabilistic procedure considering load and resistance parameters as random variables. These results are in agreement with rating factors, in which the likelihood of flexural failure is higher in comparison to shear failure.

The values in Table 5 shows the relative importance of random variables in the computed LSF for the flexural capacity and shear capacity under A160 (10%) and T44 (10%) loadings. From the comparison of the data in two different states of the Box Girder, it can be seen that proportion of the resistance on overall reliability is increased, while for LL is decreased; with marginal change for DL. Box Girder was mainly affected by load and resistance parameters due to the changes since its construction; whereas for DL and SDL minimal change is observed due to insignificant variation in the mass of the bridge. In fact, for as-designed assessment, the theoretical capacity of the bridge is obtained by nominal

values and it is compared by the nominated vehicular loading, so the basis of the design is the capability to withstand vehicular loading. Therefore, contributing variable that mostly affects the as-designed condition is the LL on bridge. However, for as-is assessment, the existing capacity of bridge is obtained by a range of values and it is compared against the nominated vehicular loading. Due to time-dependent changes in the materials properties, physical and structural conditions; the corresponding change in load and resistance parameters can be studied to identify critical parameters for any LSF and loading condition.

Table 5. Relative importance of random variables in LSF for different loading conditions

ULS		A160 (10%)			T44 (10%)		
		Resistance (%)	DL (%)	LL (%)	Resistance (%)	DL (%)	LL (%)
M	as-designed	34	< 1	65	33	< 1	66
	as-is	46	< 1	53	47	< 1	52
V	as-designed	39	< 1	60	37	< 1	62
	as-is	41	< 1	58	42	< 1	57

To allow a deeper insight into the effect of variables on the overall stability by a fully probabilistic approach, all of the parameters contributing to the flexural and shear capacities of Box Girder are considered as random variables using MCMC (refer to Table 1). Based on the calculated probability with 95% confidence interval over 6,000 data samples, it is found that the resistance of BG is not following a normal distribution, as assumed in Table 1. For A160 (10%) loading, the probability of failure ($P_f=0.0.1172$) is increased because all of the parameters affecting the flexural capacity are considered as random variables, which enables to investigate any parameter associated with uncertainty, such as uncertainty in nonlinear material properties. The ultimate shear capacity without considering shear reinforcement has $P_f=0.0265$, while this value reduces to 1.4×10^{-5} for ultimate shear capacity limited by web crushing.

Similar procedure is applicable to any combination of random variables for different limit state functions under various load effects, such as those presented in Table 4 that enables to determine the most significant parameters affecting the capacity of the bridge. Implication of the reliability analysis in Tier 4 is to fill the plausibility gap between actual and estimated LCC of the bridge. Reliability analysis in Tier 4 takes into account any noticed and unnoticed error at any stage of assessment, and qualitatively evaluates the accuracy of the estimated LCC in terms of bridge safety index and likelihood of future failure.

Conclusion and Path Forward

This study was set out to develop a comprehensive assessment framework for capacity evaluation of existing bridges, and to further refine existing practice for bridge assessment in Australia. Due to the lack of advanced assessment procedures and reliability-focused guidelines in AS 5100.7, a multi-tier assessment procedure was proposed with varying levels of the complexity to advance the existing assessment practice, and to provide a framework for higher order analysis where the results of previous assessments indicate critical ratings. Based on the LCC assessment and reliability analysis on an existing Box Girder bridge, it was observed that by using as-is information of the bridge obtained by SHM techniques, actual response of the bridge to external loading can be evaluated.

All things considered, the findings of this study provided insights into a comprehensive assessment framework that highlighted the significance of using SHM techniques for bridge assessment, and strengthened the idea that SHM techniques could be practically implemented for bridge assessment using AS 5100.7.

The future path of this study is to generalize the implication of SHM techniques for practice, not only limited to bridge assessment, but also for design and assessment of other infrastructures. To improve the productivity of freight network and Australian bridge stock, proposed multi-tier assessment procedure is very effective in enhancing the accuracy of assessment and maximizing the efficiency of freight community.

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