1	Damage onset analysis of optimized shape memory polymer composites
2	during programming into curved shapes
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27 Abstract

28 The unique shape memorizing ability of shape memory polymers (SMPs) and their fibre reinforced 29 composites have offered the prospect of remedying challenging, unsolved engineering applications. 30 Interestingly, research integrating deformable shape memory polymer composites (SMPCs) in 31 prefabricated modular constructions, deployable outer space structures and other compactable structural 32 components have emerged in the recent past. To ensure effective use in strength demanding 33 applications, SMPC components must possess better mechanical properties. Increased fibre content in 34 SMPCs will improve mechanical properties but can adversely affect the shape memory effect (SME), 35 increasing the possibility of material damage when programming into curved shapes and bends. This 36 will degrade the strength capacity of SMPCs in their applications. This paper details a complete study 37 performed on this critical effect optimizing SMPC properties by means of a 3x3 Taguchi array. The 38 study also provides an experimental framework demonstrating how these undesirable effects can be 39 mitigated coupled with an ABAQUS finite element analysis (FEA) damage prediction strategy. 40 Interestingly, the compression side of the specimen was found to be the most critical location prone to 41 programming damage. In addition, a compressive stress level of 70 MPa was found to be the damage 42 onset stress (σ_0) point for programming using FEA, and correlated with experimental results. The 43 proposed experimental and FEA framework will enhance future SMPC component design, allowing 44 researchers to predict the possibility of programming damage numerically, saving time and cost. We 45 believe that these findings will aid researchers seeking to develop strong and efficient functional SMPCs 46 for future engineering applications.

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57 **1. Introduction**

The shape memory polymer (SMP) is a functional stimuli responsive smart material with an excellent ability to memorize its original shape. When exposed to an external stimulus such as heat, electricity, light or moisture, SMP matrix softens, allowing deformation into a temporary shape [1, 2]. This smart material has the capability of holding its deformed shape until the respective stimulus is reapplied to initiate shape recovery [3]. In the SMP research context, the process of deforming a SMP into a temporary shape is often known as shape programming or training.

64 Even though SMPs have distinctive properties compared to traditional materials, inherent poor 65 mechanical properties has been their major weakness [4]. Consequently, different types of fillers and 66 fibre reinforcements were integrated with the SMP matrix to enhance mechanical properties [5-7]. The 67 matrix binds these fillers and fibre reinforcements together and distributes induced stresses through the 68 whole shape memory polymer composite (SMPC). Particulate fillers such as graphene oxide (GO) [8], 69 multi walled carbon nanotubes (MWCNT) [9], carbon black (CB) [10] and rare earth organic fillers 70 [11] produce thermal [8], electrical [9, 10] and photothermal [11] property enhancements, and fibre 71 reinforcements improve structural properties such as resistance to cyclic loading [12], modulus, 72 stiffness and strength [5]. SMPC hinges [13], truss booms [14], solar arrays [13], reflector antennas [15, 73 16], morphing structures [17, 18] and mandrels [19] are a few of the renowned applications proposed 74 for SMPCs.

75 Prefabricated modular construction is an emerging modern construction technology developed by 76 researchers and engineers to offer faster and efficient building constructions. This new trend in 77 construction has become a game changer for extremely challenging constructions in overly congested 78 cities where space is limited and time is critical. Compared to traditional construction methods, it offers 79 safer manufacturing, faster construction speeds, better quality control, fewer workers on site, less 80 resource wastage and a smaller environmental impact [20]. Importantly, in prefabricated constructions, 81 different modules of a building are manufactured in a factory and transported to the construction site. 82 These prefabricated modules are then stacked on top of each other to construct a building using cranes. 83 Despite their exciting benefits, difficulties in the transportation and handling of heavy large sized 84 modules is a major drawback in modular construction [21]. Alternatively, researchers have 85 demonstrated the ability of polymer composite materials to mitigate the heaviness of steel prefabricated 86 modules [20].

Excitingly, SMPCs are a competent substitute material for general polymer composites as they possess a temporary shape changing ability. Thus, light weight modules prefabricated with SMPCs can be heated and deformed to a compact shape in factory for easy transportation. SMPC modules can then be heated on-site to recover the initial shape and construct the building. Hence, the integration of SMPCs into structural components, panels, etc. promotes easy transportation and handling, thus mitigating the current drawbacks of prefabricated modular construction. Consequently, these SMPC components must
be deformed into curves and bends at multiple locations to achieve compact shapes. Thus, this paper
mainly aims to study the effectiveness of SMPCs during programming into such curves and bends.
Further, these compactable SMPC integrated components can also be used for emerging concepts such
as deployable structures for space habitats which can be used for space exploration [22].

97 Having sufficient mechanical properties such as tensile and compressive strengths is mandatory for 98 SMPC components. Increasing the fibre content in the composite improves its mechanical properties 99 and, as a consequence, the thickness of the composite is increased. However, the increase in thickness 100 and fibre content causes local damage, fibre buckling and delamination during shape programming 101 procedures. To the author's knowledge, significant research work investigating the adverse effects of 102 SMPCs with high thickness and fibre content has not yet been conducted. In addition, the identification 103 of damage onset stress and development of a constitutive approach to predict possible damage 104 numerically have not been studied. However, some research on fibre buckling during flexural strains 105 was carried out by Lan et al for a low thickness (2 mm) and small scaled SMPC sample (length = 30 106 mm and width = 5 mm) under high deformation curvature with low deflection (~ 0.4 mm) [23]. In 107 addition, Gall et al investigated the phenomenon of material damage during programming of a 0.3 mm 108 thick prepreg SMPC, concluding that out of plane fibre buckling and delamination must be avoided for 109 successful shape training. The selection of suitable fibre weave architecture, resin system and tow 110 spacing were suggested as possible solutions to mitigate undesirable thickness effects [24], but the 111 adverse effects on mechanical properties and ways to predict damage by any means were not 112 investigated. Interestingly, recent studies by Gu et al have proposed theoretical modelling techniques for the SME of unidirectional continuous carbon fibre SMPCs. They were based on thermodynamics 113 114 with internal state variables and refined sinusoidal shear deformation plate theory, but requires a series 115 of verification experiments to adequately prove the validity and accuracy of the models. [25, 26].

116 Our research was conducted for epoxy based, large scale SMPCs reinforced with glass, carbon and 117 basalt fibre. A 3x3 (L9) Taguchi array was developed considering the identified parameters to study 118 material damage and come up with the optimal material constituent combination for large scaled 119 samples under high deflection (15 mm). In addition, a new user-friendly damage quantifier was 120 introduced to evaluate and compare damage levels of the programmed SMPCs. Refinements in the fibre 121 orientation and programming process were implemented and tested to obtain zero areal damage 122 percentage (ADP %) and resulted in a zero drop in tensile strength after programming and recovery. 123 Additionally, σ_0 and critical stress margins (CSM) for flawless programming of the optimized SMPC 124 were proposed via ABAQUS finite element analysis (FEA) which can facilitate prompt prediction of 125 damage and critical locations. Furthermore, experimental outcomes were validated via the developed FEA numerical approach. The outcomes of the research provide firsthand knowledge and an 126

experimental framework coupled with FEA for future researchers to develop high strength SMPCstructural components for future constructions.

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130 **2. Materials and methods**

131 2.1 Materials

In this study, an epoxy based SMP was used by mixing two selected amine based hardeners with the epoxy resin in a predefined weight ratio to facilitate a stoichiometric chemical reaction. Amine based Aradur HY 951 (Triethylenetetramine) and Jeffamine D230 were used as hardeners with commercially available Bisphenol-A epoxy based resin Araldite GY 191. Evaluation of the mixing ratio of these chemicals was inspired by a previously published article [27] and, to avoid repetition, respective results and analysis have not been presented here. Thus, the selected chemical mix ratio (by weight) of GY 191 : HY 951 : D230 was evaluated as 13.03 : 1.00 : 1.63.

SMPCs were fabricated by integrating 200 gsm plain weave glass, basalt and carbon fibre fabrics as primary reinforcements. In addition, for second stage optimizing, a stitched unidirectional glass fibre fabric of areal density 500 gsm was used for reinforcement refinements to resolve recognized defects.

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2.2 Application of Taguchi method for SMPC optimization

Once the chemical composition was selected, a Taguchi array was introduced with identified parameters as a statistical approach to decide on thickness effects on the desired properties and their limitations. The Taguchi method is a robust design method frequently used in engineering applications, particularly to identify optimal process parameters by reducing the number of tests to be conducted. Table 1 illustrates the 3 x 3 experimental design with three identified parameters or factors: (1) fibre type, (2) thickness and (3) number of reinforcement layers. Selected levels of each factor are also given in Table 1.

151

	Fostors		Levels	
	F actors	1	2	3
1	Fibre type	Basalt	Glass	Carbon
2	Thickness (mm)	3	4	5
3	Number of reinforcement layers	6	8	10

152 Table 1: Selected test parameters and levels

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Specimen (SP)	Fibre type	Thickness (mm)	Number of reinforcement layers
1		3	6
2	Basalt	4	8
3		5	10
4		3	8
5	Glass	4	10
6		5	6
7		3	10
8	Carbon	4	6
9		5	8

158 Table 2: Developed L9 Taguchi array

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160 According to Table 2, nine SMPC samples were fabricated with respective thicknesses, reinforcement 161 type and number of layers. A mold with two glass plates of size 400 mm x 400 mm was used with five steel spacers of the required thickness. The sides were properly sealed with silicone to avoid polymer 162 leaks. Once the mold was ready, the three chemicals were mixed in the selected weight ratio. Then, the 163 164 SMP was degassed in a vacuum for 15 min at room temperature and poured into the mold. After curing for 24 h at room temperature, post curing was done at 100 °C for 1.5 h and 130 °C for 1 h [27]. Finally, 165 166 the SMPC sheet was demolded and cut into standard test sizes using a waterjet. Fibre mass fractions 167 (w/w %) of SMPCs were evaluated with burnout tests and the results are given in Table 3. 168

169 Table 3: Fibre mass fractions of specimens

Specimen (SP)	Fibre mass fraction (w/w %)
1	29.4
2	28.7
3	28.8
4	48.3
5	47.0
6	25.3
7	38.2
8	19.0
9	20.7

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172 **2.3 Dynamic mechanical analysis (DMA)**

- 173 Storage onset temperature (Ts) and Tan δ peak temperature (T $_{\delta}$) of materials were evaluated using TA
- 174 Instruments HR-2 Discovery Hybrid Rheometer with a dual cantilever fixture. 8 x 45 mm² sized
- samples were used to characterize the storage modulus by means of an Oscillation (temperature ramp)
- mode. A displacement of 25 μ m was applied at a frequency of 1 Hz. During the test, samples were
- heated from 20 °C to 120 °C with a temperature ramp of 5 °C/min.
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179 **2.4 Tensile and compression tests**

- 180 The SMPC's tensile and compressive mechanical properties were investigated according to standard
- 181 testing procedures using MTS 100 kN testing apparatus. Testing standards ISO 527-4:2009 and ASTM
- 182 D6641/D6641M 16 were used for tensile and compressive tests, respectively.
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184 **2.5 Shape memory effect (SME) test**



Figure 1: (a) Experimental setup (b) Initial shape of the sample (c) Programmed shape

185 Shape memory properties and the performance of selected SMPCs were studied and analyzed in terms of fixity ratio (R_f), recovery ratio (R_r) and APD %. Samples of size 100 mm x 20 mm were used to 186 evaluate the SME characteristics of each SMPC. The thermo-mechanical cycles of SMPCs were 187 implemented in MTS 10 kN testing machine along with its compatible thermal chamber as shown in 188 189 Figure 1. Programming of SMPCs were carried out at two temperatures: T_S and T_{δ} . First, a sample was 190 placed on the bending fixture with a support span of 50 mm and was allowed to heat up to its 191 programming temperature for 30 min. Then, the programming stage was initiated with two selected 192 deformation rates: (1) 1 mm/min and (2) 60 mm/min. Each SMPC was deformed bending up to a depth 193 of 15 mm at the center of its span. A piece of rubber of size $50 \times 25 \times 6 \text{ mm}^3$ was placed on the top face

194 of the SMPC during programming to increase bend radius and minimize stress concentration. After 195 programming, the thermal chamber was switched off allowing the sample to cool down to room 196 temperature. The sample was cooled for 30 min with the thermal chamber door open to facilitate 197 accelerated cooling. The force applied on the SMPC was maintained throughout the cooling process. 198 Once the sample has properly cooled, force was released to obtain the fixed temporary shape. Then, the 199 deformed SMPC was placed in an oven set to its T_{δ} for 15 min to recover initial shape. During this 200 testing procedure, photographs of the programmed, fixed and recovered shapes were taken using a 201 camera and microscope.

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203 **2.6 Damage analysis**

204 Damage levels of the tested SMPCs were quantitatively analyzed in a macro scaled perspective to 205 identify optimum material parameters. Scanning electron microscope (SEM) is a well-known 206 instrument used for the inspection of materials. However, SEM can only be carried out for a very small 207 part of the sample. In addition, tedious SEM sample preparation requires specialized equipment and the 208 process of cutting a tiny test piece from the damaged area can further damage and distort the SMPC, 209 thus affecting the reliability of test results. Hence, the proposed user-friendly technique enables quick 210 and reliable damage analysis of the programmed SMPC. The side view of the bent SMPC was used for 211 the analysis as it displays the through thickness behaviour of the material due to induced stresses while 212 bending. Thus, a dimensionless quantity ADP % has been introduced to assess samples through 213 thickness damage levels. The ADP % given in Eq. (1) compares the ratio of the damaged area (A_D) to 214 the total deformed area (A_T). Figure 2 shows: (a) the programmed shape of SP-1 at T_{δ} (~ 84 °C), (b) 215 total deformed area (A_T) and (c) damaged area (A_D). ADP % values were evaluated by measuring A_T 216 and A_D values using the measure tool in SolidWorks.

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$$ADP \% = \frac{A_D}{A_T} \times 100\% \tag{1}$$





Figure 2: (a) Programmed shape (b) Total deformed area (c) Damaged area

222 2.7 FEA analysis

223 The programming stage was simulated in ABAQUS FEA software to analyze the stress distribution 224 within the sample. As SMP/SMPC programming takes place within the transition region, the material 225 will have a mix of both elastic and viscous properties. Hence, the programming step was defined as a 226 "visco" step with "viscoelastic" material property which was previously studied by Azzawi et al (2017) 227 [28]. As suggested, Prony series relaxation data extracted from DMA Q800 were used to define the 228 viscoelastic properties of the material. In addition, tensile properties at the programming temperature 229 are required to define SMPC material properties. The experimental programming test was simulated in 230 ABAQUS for a SMPC of size 100 mm x 20 mm x 3 mm.

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232 **3. Results and discussion**

233 **3.1 Material properties**

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3.1.1 Dynamic Mechanical Analysis (DMA)

For SMPCs to be used in the structural components of modular constructions, having a T_g higher than average environmental temperature is mandatory. In addition, SMPC properties start dropping when heated beyond T_g . Thus, the T_g of a SMP is one of the key characteristics which outline a material's performance range and limitations. Therefore, DMA tests were carried out to identify this critical temperature value.

240 In the SMP context, T_g is also referred to as the temperature at which both programming and recovery 241 are undertaken. However, the definition of Tg is not certain among SMP research. In general, for all 242 one way SMPs, the higher the temperature of the sample, the easier the programming. Conversely, 243 programming at higher temperatures is not always favourable due to a higher consumption of energy 244 and time. Thus, research suggests that SMP shape training can be categorized into different temperature 245 ranges as cold (below T_s), warm (T_s to T_{δ}) and hot programming (above T_{δ}) [29, 30]. Feldkamp et al 246 investigated the effect of deformation temperature on the ultimate deformation strain (\mathcal{E}_{III}) of an epoxy 247 shape memory pristine polymer under tension and concluded that ε_{UL} can be increased 3 to 5 folds at T_{S} [31]. Hence, T_{S} and T_{δ} which lie within the borders of the warm temperature region were selected 248 249 for this study. Figure 3 shows the characterization of the storage modulus and Tan δ of SP-1. The 250 transition values T_S and T_δ of SP-1 were found to be 58 °C and 83.8 °C, respectively. According to 251 Table 4, it can be seen that respective transition temperatures have changed with the specimen 252 constituents. This suggests that SMPC's thermomechanical characteristics depend on material 253 composition defined by their thickness, fibre type and number of reinforcement layers. 254



Figure 3: DMA results characterizing the storage modulus and Tan δ of SP-1

255

256 *Table 4: Transition temperatures of samples*

Specimen (SP)	Ts (°C)	$T_{\delta}\left(^{o}C\right)$
1	57.6	83.8
2	59.7	86.9
3	57.6	88.4
4	60.0	81.9
5	55.4	82.5
6	58.9	85.9
7	59.5	83.9
8	53.2	84.7
9	59.4	85.2

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258 **3.2 L9 Taguchi analysis**

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3.2.1 Shape memory and mechanical properties

• Shape fixity and recovery ratios

Shape memory performance of SMPs is commonly studied in terms of R_f and R_r [32-34]. The R_f shows the extent to which a material can hold its deformed shape when the external force is removed, while R_r relates to the amount of shape recovered. The study of these shape memory parameters is vital in proposed SMPC applications. That is, deformed SMPC structural components produced in factories should be capable of retaining their deformed shape during transportation to construction sites. Then, upon heating on-site, maximum recovery is expected for module assembling. Hence, these crucial parameters of the developed test samples were measured and analyzed to achieve maximum shapememory performance of the optimized material.

269 Table 5 provides the evaluated R_f % and R_r % values of all nine SMPC specimens. During SME testing, 270 some samples experienced cracking, with fibre damage mostly at the lower temperature T_s (given by 271 "X"). The reasons for such phenomenon and other possible damage types are discussed in the "damage 272 analysis" section of this article. At a given temperature (as in Table 5), evaluated values are different to 273 one another and it is evident that material composition defined by the thickness, fibre type and fibre 274 content has affected shape memory performance despite having the same polymer matrix. This can be 275 attributed to the changes in fibre matrix bond characteristics, reinforcement mechanical properties and 276 bending stress distribution through the thickness. In addition, higher R_f% and R_r% values were obtained 277 at the higher temperature T_{δ} compared to T_{S} . This is due to a high loss of material stiffness as the 278 material approaches the rubbery phase [35], allowing the material to store more strain energy when 279 deformed. However, programming at higher temperatures caused material defects in SMPC specimens, 280 which is a significant drawback in terms of SMPC material performance and application.

281

282 Table 5: Fixity and recovery ratios of samples at two selected transition temperatures

		Prog	camming	
Specimen (SP)	At T	Cs (°C)	At T	['] δ (°C)
	Rf %	Rr %	R _f %	R r %
1	91.7	93.0	99.0	95.4
2	Х	Х	95.3	96.9
3	Х	Х	96.7	97.3
4	91.4	90.4	95.8	91.5
5	96.4	86.4	79.2	90.6
6	Х	Х	92.9	92.6
7	Х	Х	86.2	95.2
8	Х	Х	93.9	94.7
9	Х	Х	Х	Х

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• Mechanical properties of SMPCs

288 Superior shape memory properties alone cannot transform SMPCs highly competent compared to 289 traditional materials. Having adequate mechanical properties is a vital factor for SMPCs to outrace 290 performance of other common materials in construction engineering applications. Consequently, the 291 SMPC tensile and compressive properties were analyzed and considered as output variables of the 292 Taguchi L9 analysis. Figure 4(a) shows the tensile properties of the test samples in terms of tensile 293 strength and elastic modulus. Among all test samples, carbon fibre reinforced SMPCs showed the best 294 tensile properties due to the superior material properties of the carbon fibre reinforcement [22]. 295 However, basalt SMPCs have almost the same tensile properties as glass fibre SMPCs, even with 296 comparatively low fibre fractions. This is due to the better structural properties of the basalt fibre 297 compared to E-glass reinforcement [36]. A slight variation among the tensile values of basalt SMPCs 298 can be seen due to almost similar fibre weight fractions (29.4 %, 28.7 % and 28.8 %). Moreover, SP-4 299 and SP-5 with the highest fibre weight fraction of the glass samples have similar tensile properties, 300 while SP-6 with the lowest fibre content of 25.3 % showed the weakest properties. Interestingly, both 301 tensile strength and elastic modulus showed a similar trend and demonstrated a proportional relationship 302 between tensile characteristics and fibre content.

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304 The variation in compressive strength and moduli of test samples are illustrated in Figure 4(b). 305 Compared to tensile properties, carbon fibre SMPCs did not show a significant improvement under 306 compressive loading with respect to other reinforcements. However, as in tensile properties, an almost 307 identical trend can be seen between compressive strength and its modulus. Thus, these results agree 308 with the claim that an increase in fibre content (or fraction) results in the enhancement of the SMPC's mechanical properties [37]. Most importantly, evaluated tensile and compressive properties of the 309 specimens have shown better mechanical properties and structural capability compared to structural 310 characteristics of other previously studied SMPCs [38, 39], exhibiting their potential to be integrated in 311 312 deformable structural components.



Figure 4: Mechanical properties of SMPC specimens. (a) Tensile and (b) Compressive material properties

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315 **3.2.2 Damage analysis**

The SME of a shape memory material makes it distinct and effective compared to traditional materials. Hence, the SME of these functional materials should be flawless to be used effectively in challenging applications. The SMPs and their composites are expected to deform at a suitable transition temperature under the applied load, leaving no damage to the shape memory component. Such undesirable damage during programming can result in the weakening of SMPC components.

321

322 During the shape training process, the heated SMP will be in a flexible but weak rubbery state due to 323 matrix softening and degradation [40]. Hence, the matrix-fibre interface which supports fibres and 324 engages in stress transfer when loaded, will be weakened [41-43]. Consequently, the interfacial bond 325 strength between matrix and fibre will be in a weak state during programming. In addition, the failure 326 mode and strength capacity of the polymer composite will rely on the interfacial bond strength [41, 44] 327 which is a crucial factor for SMPC programming. Interestingly, the stress at the onset of damage has 328 been introduced as a measure of interfacial bond strength of the composite [41]. Hence, even reinforced 329 SMPCs might not have enough strength to withstand the deformation strain levels. In such cases, the 330 material is prone to damage due to deformation strains induced whilst programming. In addition, these 331 undesirable effects become prominent as the material thickness increases. Hence, the investigation of 332 material damage in the programming stage of SMPCs is vital to develop versatile future smart 333 components.

According to the results, thicker SMPC samples with high fibre volume fraction resulted in high damage levels. Specially, irrespective of the temperature, carbon SMPCs have shown weakest programmability due to high stiffness. This is due to significant improvement gained in stiffness and other mechanical properties by carbon fibre integration compared to other fibre types.

Even though most of the samples cracked with severe material damage at T_s , few glass and basalt SMPCs displaced significantly low ADP % values. The damage levels of the specimens SP-1, SP-4 and SP-5 which performed best during the programming process with better damage resistance are presented in Figure 5 for comparison. Hence, T_s can be concluded as the best transition temperature to program SMPCs to minimize possible material damage. This was also suggested by Feldkamp et al [31] for a neat flexible SMP under tensile loading.

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Figure 5: Comparison of ADP % values of SP-1, SP-4 and SP-5 at two transition temperatures

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Types of damage and locations

348 By studying the behaviour of SMPCs during programming, three types of damage were identified: (1) 349 Type 1 - Internal fibre micro-buckling and debonding, (2) Type 2 - Delamination and (3) Type 3 -Through thickness cracking. Type 1 damage was observed at both temperatures T_S and T_δ, but only on 350 351 the compressed side of the sample. Moreover, higher temperatures facilitated Type 1 damage due to the 352 soften polymer matrix. Type 2 SMPC damage was also detected at both temperatures, mostly at the 353 central region closer to the compressed side of the specimen. However, samples showed severe Type 2 damage at the higher temperature T_{δ} . High SMP stiffness at the lower temperature T_S resulted in Type 354 355 3 damage in samples with high thickness and fibre fraction. The chance of Type 3 damage increases at 356 lower temperatures and it initiates at the tensioned side of the specimen. Of the three identified damage 357 types, Types 1 and 2 were the most common as they occurred at both temperatures. 358

359 **3.2.3 Taguchi optimization**

Taguchi optimization can be carried out to maximize or minimize responses by the larger-the-better or the smaller-the-better criteria, respectively. For our application, maximizing almost all material parameters are favorable for SMPC performance. However, the ADP % damage quantifying factor should be minimized to achieve the best SMPC functionality. Therefore, a modified response (1/ADP %)_{MAX} was introduced as an alternative to (ADP %)_{MIN}. Thus, by modifying the response for damage as 1/ADP, optimization analysis was easily carried out with the larger-the-better principle. Minitab 18 software was used to perform the Taguchi analysis and generate signal to noise (S/N) ratio plots.

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For best overall material properties

Taguchi optimization was also carried out for the test series considering T_S , T_δ , R_f , R_r , 1/ADP %, σ_T , E_T, σ_C and E_C as responses to investigate most suitable SMPC parameters and achieve the best overall material properties (for both shape memory and mechanical). Table 6 presents the evaluated S/N ratios of the analysis, and the respective plot is given in Figure 6. Interestingly, the material parameters: glass fibre, 3 mm and 6 layers, were found to be the best constituents to achieve both shape memory and structural performance. Consequently, further tests included in this research were based on these selected SMPC parameters.

377Table 6: Response table for signal to noise ratios for overall SMPC performance378considering T_s , T_{δ} R_f , R_r , 1/ADP, σ_T , E_T , σ_C and E_C

Level	Fibre type	Thickness	No of layers
$T_{S}, T_{\delta}, R_{f},$	R_r , 1/ADP, σ_T , E_T , c	σ_{C} and E_{C} : S/N ratios (Larger is better)
1	-16.718	-7.041	-16.718
2	-30.459	-24.632	-20.782
3	-14.956	-30.459	-24.632
Delta	15.503	23.417	7.914
Rank	2	1	3



Figure 6: S/N ratios of T_s , T_{δ} , R_f , R_r , 1/ADP, σ_T , E_T , σ_C and E_C for overall SMPC performance

379

380 **3.3 Reinforcement modification**

381 From the above Taguchi analysis, properties of specimens were optimized within the selected factors 382 and levels. The analysis was done using the same reinforcement architecture in all tested samples. From 383 this analysis, optimum material parameters were proposed to achieve the lowest possible damage level 384 (but not ADP % = 0). However, even a minor damage level experienced in a programming stage could 385 lead to a considerable drop in the material's mechanical properties and hinder performance of SMPC structural components. Therefore, having zero ADP % is mandatory for successful SMPC integrated 386 387 applications. As a result, the fibre reinforcement architecture of the optimized SMPC was modified as a further refinement to enhance the SME without creating a reduction in strength. These further 388 modifications aimed to achieve two objectives: (1) prevent any visible cracks (through thickness) and 389 390 (2) ensure no change to the material's ultimate strength after shape programming. Two selected 391 refinement strategies were implemented in order to achieve above mentioned objectives: (1) 392 reinforcement orientation and architecture adjustment and (2) programming method parameter change. 393 The optimum thickness of 3 mm and total number of layers (6 layers) were maintained along with the 394 above refinements.

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3.3.1 Performance of two unidirectional fibres on either side (SP-10)

As explained in Section 3.2.2, to avoid the buckling or wrinkling of fibres, a new specimen (SP-10) was tested with unidirectional fibre layers placed on the outermost faces in the transverse direction, as illustrated in Figure 7. Then, the programming efficiency of the SP-10 sample was tested at T_s and T_δ . ADP % of SP-10 at T_s and T_δ were calculated as 1.1 % and 19.6 %, respectively. As predicted, the damage level was lowest at T_s . Interestingly, sample SP-10 showed an outstanding improvement, with no damage on the compression side preventing formation of reinforcement wrinkles with microbuckling. However, a few cracks were seen on the tension side of the bent SP-10 sample (as shown in 404 Figure 7). This can be attributed to the fibres oriented perpendicular to the tensile loads which created
405 a directional weakness allowing SP-10 to crack on the tensioned side. Hence, SP-11 with only one
406 unidirectional reinforcement on the compression side was fabricated and tested to achieve zero ADP
407 %.

408



Figure 7: Visible damage analysis of SP-10 with a reinforcement refinement (a) Deformed shape (b) Area of damage

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410 **3.3.2** Performance of unidirectional fibre on the compression side (SP-11)

411 Figure 8 shows a deformed SP-11 specimen with a unidirectional reinforcement layer positioned on the 412 compression side of the sample. The remaining five layers did not change and were maintained as plain 413 weave fabrics. According to the findings above, specimen SP-11 was programmed at the most effective 414 temperature T_s . As depicted in Figure 8, a single unidirectional layer made a significant improvement 415 in terms of damage resistance, and resulted a zero ADP %. Hence, visible damage (in Objective 1) was 416 effectively prevented by means of appropriate adjustments in the reinforcement architecture. However, 417 the SMPC should be able to retain its initial strength having gone through a complete shape memory 418 thermomechanical cycle.

419

420 **3.4 Evaluation of tensile properties after shape programming and recovery**

421 **3.4.1 Tensile properties of SP-11**



Figure 8: Programming of SP-11 with no visible damage

423 Tensile tests were carried out to evaluate the retained strength of the programmed and recovered 424 samples. That is, to understand the impact of material programming on the structural characteristics of 425 SMPCs. The stress (σ) – strain (ϵ) curves of programmed SMPCs after recovery and original sample 426 are given in Figure 9. According to Taguchi optimization, basalt fibre was found to be the second best 427 option for a low ADP % value. Hence, tensile test results of both glass and basalt SMPCs are included 428 in Figure 9 for a comparison. Also, the same programming conditions used for the Taguchi damage and SME analysis were used in the shape training process of the SP-11 specimen. The notation "GL" and 429 430 "B" stand for glass and basalt SMPCs.



Figure 9: Tensile σ - ε curves of glass and basalt SP-11 before and after programming

431

432 As in Figure 9, both glass and basalt fibre composites showed similar properties and σ - ε behaviour 433 under tensile loading. They also displayed an almost identical initial tensile strength of 122.9 MPa and 434 121.3 MPa respectively. Additionally, initial elastic moduli (E) were evaluated as 9.2 GPa and 9 GPa 435 respectively for glass and basalt SMPCs. However, a drastic drop in tensile properties was observed in both programmed and recovered specimens. Table 7 gives a summary of the test results of both types 436 437 of SMPCs before and after undergoing a complete thermomechanical cycle. The glass SMPC showed 438 a 37 % and 10 % reduction in tensile strength and elastic modulus respectively. Moreover, the basalt 439 SMPC experienced a 40 % and 18 % decline (σ and E) in tensile properties after programming. This can be attributed to internal minor loosening (Type 1) and separating of fibres (Type 2) due to a 440 441 concentration of stress and loss of adhesion with the polymer matrix during SMPC programming. This 442 phenomenon has reduced the amount of effective reinforcement in the SMPC which can withstand 443 tensile loads, and hence resulted in a premature failure. Interestingly, reinforcement refinement 444 minimized the severity of both Type 1 and 2 damage which had occurred at a small scale. Furthermore, 445 these minor flaws were present between laminae inside the material which did not affect the visible

damage quantifier ADP %. Hence, having a zero ADP % does not guarantee the perfect retainment of
mechanical properties after recovery. Even though ADP % = 0 is mandatory to prevent visible cracks
in the sample, identified minor flaws such as debonding between the fibres and matrix must be
eliminated during the programming stage to avoid any decline in mechanical properties.

450

451	Table 7: A	summary of ten	sile test results	of SP-11	samples	before d	and after	programmin	ıg
-		···· · · · · · · · · · · · · · · · · ·		- J	T T	· · · · · ·	······································	r . o	0

SMDC	Init	Initial		After programming		Reduction %	
SMPC	σ (MPa)	E (GPa)	σ (MPa)	E (GPa)	Δσ %	ΔE %	
Glass	122.9	9.2	78.0	8.3	37	10	
Basalt	121.3	9	72.7	7.4	40	18	

452

453 **3.5 Programming method modification**



Figure 10: Programming of SP-11-D50 with the refinement in programming process

454

455 Stress concentrated in the bending region facilitated the debonding of fibres with the soft polymer matrix at the programming temperature. To achieve both ADP % = 0 and $\Delta \sigma \% = 0$, a further refinement 456 457 is required to eliminate internal fibre debonding and, hence, retain initial material structural properties. 458 As the thickness of SMPC is constant throughout the sample, stress concentration can only be reduced through an adjustment to programming process parameters. Increasing the support span or bend radius 459 460 of the specimen will help to distribute bending stresses throughout the sample, allowing it to deform 461 easily with minimal internal damage. Figure 10 illustrates the adjusted programming process with a 50 mm (five folds higher than previous) diameter deforming tool. Figure 12 presents σ - ϵ curves of glass 462 and basalt SMPCs programmed under the modified process and named as "D50". Most importantly, 463 recovered samples showed an almost identical tensile strength as their initial properties. Both 464

465 composites displayed a negligible decline in tensile strength of 0.9 % and 0.1 %. Moreover, the strain 466 at break of both SMPCs increased, proving an improvement in material elasticity. The decline in elastic 467 modulus also showed an improvement compared to the previous tests, however recovered glass and 468 basalt fibre composites showed 9 % and 10 % modulus reduction respectively. The existence of a few 469 locations with minor Type 1 damage with internal fibre debonding (as in Figure 11 (c)) caused this 470 slight drop in modulus. This claim has been validated numerically with the help of the developed FEA 471 approach (discussed in Section 4). In addition, the increased elasticity of the material adversely affected 472 the reduction in elastic modulus of the SMPCs. Figure 11 depicts a deformed glass SMPC with new programming process parameters. Table 8 and Figure 13 present a summary of the evaluated results 473 474 and clearly demonstrate significant improvement in SMPC performance even after shape recovery. 475 With the refinements introduced, both visible damage level and strength drop could be mitigated which 476 will eventually enhance SMPC performance in future prospective applications.

477

478



Figure 11: SP-11-GL-D50 sample photographs after programming

479



Figure 12: Tensile σ - ε curves of glass and basalt SP-11-D50 before and after programming

480

Initial After programming **Reduction % SMPC ΔE %** σ (MPa) E (GPa) σ(MPa) E (GPa) Δσ % Glass 122.9 9.2 121.8 8.4 0.9 9 9 Basalt 121.3 121.2 8.1 0.1 10



485



Figure 13: Comparison of reductions in tensile strength and modulus of SP-11 and SP-11-D50 glass and basalt SMPCs

486

487 **4.** Numerical validation of experimental results

488 4.1 Validation of results via ABAQUS FEA model

A numerical simulation was implemented in ABAQUS to investigate induced stress distribution in the 489 490 optimized SMPC during the programming stage and develop a damage prediction strategy. In keeping 491 with the scope of the article, only the programming stage of SMPCs is analyzed here. Figure 14 presents 492 the modelled assembly with initial and programmed shapes. Experimental results (load versus time) 493 extracted from the MTS 10 kN testing equipment and calculated flexural stress during the programming 494 stage of SP-11 were used to validate the FEA approach implemented in ABAQUS. Figure 16(a) and (b) 495 show the comparison of the maximum flexural stress magnitude and load due to the programming of 496 the glass sample SP-11-GL. The curves fit perfectly until Point 1 (Figure 16) where the Type 1 SMPC 497 damage begins. Type 1 damage developed until a displacement of 7 mm (Point 2) where Type 2 damage

498 occurred, further reducing the load. Hence, by matching this scenario, CSMs can be introduced to499 predict the occurrence of Types 1 and 2 damage from FEA results.

500



Figure 14: Shape programming in ABAQUS (a) Initial shape (b) Programmed shape

501

502 Most importantly, for the best SMPC performance, a zero damage level is mandatory. Thus, a numerical 503 analysis should be developed to predict σ_0 which can then be used as a tool to predict whether damage 504 in the programming stage is likely or not. Hence, it can be concluded that σ_0 as the most critical factor 505 for SMPC programming. As the model does not take into account the behaviour of post damage, 506 interfacial bond properties and progressive failure of SMPCs, FEA results do not match with the 507 experimental data beyond Point 1. However, if needed, properties of the nanoscale matrix-fibre 508 interface and mechanics of stress transfer can be analyzed using shear lag theory and traction-separation 509 law as previously studied by Budurapu et al (2019) [45] and Skovsgaard et al (2021) [46]. This analysis 510 is not included here as it is not within the scope of the article.

511

512 Therefore, a compressive stress of 70 MPa (= σ_0) should not be exceeded during programming to avoid 513 all types of damages at T_s . Thus, the interfacial bond strength of the SMPC can also be described as 70 514 MPa [41]. Moreover, stress values from 70 MPa to 100 MPa will cause Type 1 damage, and Type 2 515 damage will develop beyond 100 MPa (given in Figure 17). Hence, the selected CSM facilitates prompt 516 prediction of programming effectiveness of the SMPC, enables selection of the most suitable 517 programming parameters through FEA, and saves time. Figure 18 illustrates the FEA stress results of 518 the SP-11-GL-D50 with 60 mm span described in Section 3.5. According to the proposed CSM, it is 519 evident that the SMPC reached the Type 1 damage region which resulted a decline in modulus. 520 However, as the maximum stress is well below the Type 2 region, no change in strength can be expected. 521 The respective FEA results of SP-11 and SP-11-GL-D50 are given in Figure 15, where $S_{11} = S_{xx} =$ 522 flexural stress. These FEA results and damage predictions validate the experimental observations and 523 outcomes which can be effectively applied in future SMPC developments.



Figure 15: Stress variation of programmed samples (a) SP-11 before programming (b) Programmed SP-11 (c) SP-11-D50 before programming (d) Programmed SP-11-D50

525 526



Figure 16: Comparison of experimental and FEA (a) Average compressive stress magnitude at the most critical location of the SMPC (b) Applied load for programming

527



Figure 17: Critical stress margins introduced to predict programming effectiveness through FEA

Type 1 Damage Flexural Stress (MPa) SP-11-GL-D50 d (mm)

Figure 18: FEA stress results for the shape programming process of SP-11-GL with 50 mm bend diameter

5. Conclusion

A novel user-friendly approach to quantify damage has been introduced and implemented in this research to identify damage incorporated in SMPCs during shape programming. It was revealed that high SMPC thickness and reinforcement content adversely affects the effectiveness of the shape programming process, resulting in material flaws. A new dimensionless quantity (ADP %) has been introduced and can be used by researchers as a user friendly through thickness visible damage quantifier in SMPCs when programming. A robust Taguchi L9 array was implemented to achieve the lowest ADP % along with the best possible mechanical properties. Further, two refinements in the reinforcement architecture and programming process were proposed and tested to achieve ADP % = 0 and no decline in ultimate tensile strength ($\Delta \sigma = 0$ %). From the analysis, three types of SMPC damage were identified and the material's compression side was also identified as the most critical location susceptible to damage while programming. The best programming characteristics for optimum performance were shown at the low temperature T_s (~ 60 °C) coupled with a higher deformation rate (60 mm/min). The best combination of SMPC material parameters was evaluated as glass fibre reinforcement, 3 mm and 6 layers (5 plain weave + 1 unidirectional layer on the compression side with fibres in the transverse direction). In addition, experimental results were validated using FEA analysis and CSM guidelines were proposed to predict possible damage levels during programming. Hence, 70 MPa was found to be the σ_0 or interfacial bond strength of the optimized glass SMPC to undergo perfect programming. Overall, the study provides first hand comprehensive programming damage investigation of SMPCs including a novel experimental and numerical framework to optimize and design SMPC integrated structural components for future constructions.

569 6. References

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